



Kubios HRV

version 2.0

<http://kubios.uku.fi>

USER'S GUIDE

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Contents

1	Overview	4
1.1	System requirements	5
1.1.1	Windows	5
1.1.2	Linux	5
1.2	Installation	5
1.2.1	Windows	5
1.2.2	Linux	5
1.3	Uninstallation	6
1.3.1	Windows	6
1.3.2	Linux	7
1.4	Software home page	7
1.5	Structure of this guide	7
2	Heart rate variability	9
2.1	Heart beat period and QRS detection	10
2.2	Derivation of HRV time series	11
2.3	Preprocessing of HRV time series	13
2.3.1	Smoothness priors based detrending approach	13
3	Analysis methods	15
3.1	Time-domain methods	15
3.2	Frequency-domain methods	16
3.3	Nonlinear methods	16
3.3.1	Poincaré plot	17
3.3.2	Approximate entropy	18
3.3.3	Sample entropy	18
3.3.4	Detrended fluctuation analysis	19
3.3.5	Correlation dimension	20
3.3.6	Recurrence plot analysis	21
3.4	Summary of HRV parameters	23
4	Software description	25
4.1	Input data formats	25
4.2	The user interface	25
4.2.1	RR interval series options	25
4.2.2	Data browser	27
4.2.3	Analysis options	29
4.2.4	Results view	30

4.2.5	Menus and toolbar buttons	31
4.3	Saving the results	33
4.3.1	ASCII-file	33
4.3.2	Report sheet	33
4.3.3	MATLAB® MAT-file	35
4.4	Setting up the preferences	36
5	Sample runs	40
5.1	Sample run	40
A	Frequently asked questions	46
B	Troubleshooting	48
B.1	Windows specific	48
B.2	Linux specific	49
	References	49

Chapter 1

Overview

Kubios HRV is an advanced tool for studying the variability of heart beat intervals. Due to its wide variety of different analysis options and the easy to use interface, the software is suitable for researchers and clinicians with varying premises. The software is mainly designed for the analysis of normal human HRV, but should also be usable, e.g., for animal research.

Kubios HRV includes all the commonly used time- and frequency-domain variables of HRV. The frequency-domain variables are calculated for both nonparametric (Fourier transform based) and parametric (autoregressive modeling based) spectrum estimates. In addition, several nonlinear HRV variables are calculated such as Poincaré plot, recurrence plot analysis, detrended fluctuation analysis, approximate and sample entropies, and correlation dimension.

The Kubios HRV, heart rate variability (HRV) analysis software¹, is developed by the Biosignal Analysis and Medical Imaging Group (BSAMIG) at the Department of Physics, University of Kuopio, Kuopio, Finland. The software is a considerable upgrade to the previous version (version 1.1) of the software described in [32]. Changes from the previous version include significantly improved usability, support for new data formats and many new or updated features. Kubios HRV has been developed using MATLAB® Release 2008a (The MathWorks, Inc.) and was compiled to a deployable standalone application with the MATLAB® Compiler 4.8. The MATLAB® Compiler Runtime (MCR) version 7.8 is required for running Kubios HRV and is included in the Kubios HRV installers.

¹Kuopio University has only limited rights to the software. These limited rights are governed by a certain license agreement between Kuopio University and The MathWorks, Inc.

1.1 System requirements

The system requirements given below should be considered as recommended system requirements. The software may work also with lower system specifications, but will probably function slower or with reduced usability.

1.1.1 Windows

- Operating system: Microsoft® Windows 2000, XP or Vista
- Processor: Intel® Pentium 4 and above (or equivalent 32-bit (x86) processor)
- Memory: 512 MB of RAM (1024 MB or higher recommended)
- Disk space: about 500 MB
- Desktop resolution of 1024×768 or higher
- The MATLAB® Compiler Runtime 7.8 (included in the Kubios HRV installer)

1.1.2 Linux

- Operating system: a Linux distribution with kernel 2.4.x or 2.6.x and glibc (glibc6) 2.3.4 and above.
- Processor: Intel® Pentium 4 and above (or equivalent 32-bit (x86) processor)
- Memory: 512 MB of RAM (1024 MB or higher recommended)
- Desktop resolution of 1024×768 or higher
- Disk space: about 460 MB
- The MATLAB® Compiler Runtime 7.8 (included in the Kubios HRV installer)

1.2 Installation

1.2.1 Windows

Make sure that you have administrator privileges and run the Kubios HRV installer file. Follow the instructions given in the setup wizard to complete installation. You can launch the Kubios HRV by selecting it from the created Start Menu folder or by clicking the Desktop icon (if created). Please note that the starting of Kubios HRV also starts the MATLAB® Compiler Runtime and may take some time especially with older computers.

1.2.2 Linux

Run the Kubios HRV installer by typing `sh KubiosHRV-linux-2.0.x86.run` in the terminal and follow the instructions given on screen. The Kubios HRV installer also includes the MATLAB® Compiler Runtime. **NOTE: If you run the installer as root, Kubios HRV will be installed on your computer system wide for all users. If you want to install Kubios HRV only for yourself, run the installer as local user.**

1.3 Uninstallation

The Kubios HRV can be uninstalled either automatically using the uninstaller or manually if the uninstaller fails for some reason. Both methods for uninstallation are described in the following.

1.3.1 Windows

Automated uninstall

The preferred and the most straightforward way of uninstalling Kubios HRV is to use the automated uninstaller. The uninstaller can be launched by selecting “Uninstall Kubios HRV” from the software’s Start menu folder (the default Start menu folder is Kubios HRV). The software can also be uninstalled from the “Add or Remove Programs” under the Windows Control Panel. The uninstaller does not remove your preferences settings. These have to be deleted manually from `C:\Documents and Settings\<username>\Application Data\KubiosHRV`.

Manual uninstall

The manual uninstallation should be conducted only if the automated uninstallation fails. The Kubios HRV can be completely uninstalled manually by deleting the following files, folders, and registry entries:

- Delete the install folder (by default `C:\Program Files\Kubios HRV`) and all the sub-folders and files in it.
- Delete the KubiosHRV folder (if exists) from
(Windows XP/2000:) `C:\Documents and Settings\<username>\Application Data\`
(Windows Vista:) `C:\Users\<username>\AppData\Roaming\`
- Delete the Kubios HRV quick launch icons (if exist) from
(Windows XP/2000:) `C:\Documents and Settings\<username>\Application Data\Microsoft\Internet Explorer\Quick Launch\`
(Windows Vista:) `C:\Users\<username>\AppData\Roaming\Microsoft\Internet Explorer\Quick Launch\`
- Delete desktop icons (if exist) from
(Windows XP/2000:) `C:\Documents and Settings\All Users\Desktop\`
(Windows Vista:) `C:\Users\Public\Desktop\`
- Delete the possible Start menu entries from
(Windows XP/2000:) `C:\Documents and Settings\All Users\Start Menu\Programs\`
(Windows Vista:) `C:\ProgramData\Microsoft\Windows\Start Menu\Programs\`



- Remove the MATLAB Compiler Runtime entry (`<KubiosHRV install dir>\MCR\v78\runtime\win32`) from the system path
- Manual removal of the Kubios HRV Analysis entry from the Windows' "Add or Remove Programs" list requires modifying registry. A thorough instructions on how to manually remove programs from the "Add or Remove Programs" list is available on the Microsoft support web site at <http://support.microsoft.com/?kbid=314481>.

1.3.2 Linux

Automated uninstall

Open terminal and change directory to the Kubios HRV install directory. Run the command `sh uninstall_kubios.sh` and follow instructions given on screen. NOTE: You may need root privileges for running the uninstaller if you have installed Kubios HRV as root.

Manual uninstall

Open a terminal and run the following commands. In the commands replace `<Kubios HRV install dir>` with the Kubios HRV install directory. NOTE: You may need root privileges for running these commands if you have installed Kubios HRV as root.

- Uninstall Kubios HRV menu entries
`xdg-desktop-menu uninstall <Kubios HRV install dir>/BSAMIG-KubiosHRV.desktop`
- Uninstall Kubios HRV desktop icons
`xdg-desktop-icon uninstall <Kubios HRV install dir>/BSAMIG-KubiosHRV.desktop`
- Delete the Kubios HRV install directory
`rm -rf <Kubios HRV install dir>`

1.4 Software home page

The Kubios HRV (version 2.0) home page on the web can be found at

<http://kubios.uku.fi/>

where you can find current information on the software and download possible updates and related material.

1.5 Structure of this guide

The aim of this guidebook is to help the user to get started with Kubios HRV. It should not, however, be thought of as being an easy to follow step by step manual, but more like a reference material from which you can probably find answers to your problems related to HRV analysis or usability of the software. The structure of this guide is as follows.

After the overview chapter, from where you will find useful information about the system requirements and installation, an introduction to heart rate variability is given in Chapter 2. This chapter starts with a short discussion on the control systems of heart rate after which the extraction of heart beat periods is discussed and the derivation of HRV time series is

described. The rest of the chapter is focused on the preprocessing of HRV data and gives a detailed description of the smoothness priors based detrending approach.

In Chapter 3, the analysis methods included in the software are described. The descriptions of the methods are divided into time-domain, frequency-domain, nonlinear, and time-varying categories and a summary of the methods is given at the end of the chapter. For most of the methods, exact formulas for the different variables are given and possible parameter selections are pointed out.

In Chapter 4, the description of the features and usage of the software is given. First, the input data formats supported by the software are described and then the user interface through which the software is operated is described. Then, different options for saving the analysis results are described and, finally, instructions on how to set up the preference values for the analysis options are given.

In Chapter 5, two sample runs of the software are presented. The first sample run describes how to analyze the lying and standing periods of the orthostatic test measurement (distributed along this software) separately as stationary segments. The second sample run, on the other hand, describes the time-varying analysis procedure of the same measurement.

In Appendix A, some frequently asked questions with answers are given. The questions are selected based on the feedback obtained from the users of the previous version of this software.

Finally, in Appendix B, workarounds for some commonly encountered technical problems are given.



Chapter 2

Heart rate variability

Heart rate variability (HRV) describes the variations between consecutive heartbeats. The rhythm of the heart is controlled by the *sinoatrial* (SA) node, which is modulated by both the sympathetic and parasympathetic branches of the autonomic nervous system. Sympathetic activity tends to increase heart rate (HR $\uparrow$) and its response is slow (few seconds) [3]. Parasympathetic activity, on the other hand, tends to decrease heart rate (HR $\downarrow$) and mediates faster (0.2–0.6 seconds) [3]. In addition to central control, there are some feedback mechanisms that can provide quick reflexes. One such mechanism is the arterial baroreflex. This reflex is based on baroreceptors which are located on the walls of some large vessels and can sense the stretching of vessel walls caused by pressure increase. Both sympathetic and parasympathetic activity are influenced by baroreceptor stimulation through a specific baroreflex arc, Fig. 2.1.

The continuous modulation of the sympathetic and parasympathetic innervations results in variations in heart rate. The most conspicuous periodic component of HRV is the so-called *respiratory sinus arrhythmia* (RSA) which is considered to range from 0.15 to 0.4 Hz [3]. In addition to the physiological influence of breathing on HRV, this *high frequency* (HF) component is generally believed to be of parasympathetic origin. Another widely studied component of HRV is the *low frequency* (LF) component usually ranging from 0.04 to 0.15 Hz including the component referred to as the 10-second rhythm or the Mayer wave [3]. The rhythms within the LF band have been thought to be of both sympathetic and parasympathetic origin [3] even though some researchers have suggested them to be mainly of sympathetic origin [25]. The fluctuations below 0.04 Hz, on the other hand, have not been studied as much as the higher frequencies. These frequencies are commonly divided into *very low frequency* (VLF, 0.003–0.04 Hz) and *ultra low frequency* (ULF, 0–0.003 Hz) bands, but in case of short-term recordings the ULF band is generally omitted [45]. These lowest frequency rhythms are characteristic for HRV signals and have been related to, e.g., humoral factors such as the thermoregulatory processes and renin-angiotensin system [3].

Even though HRV has been studied extensively during the last decades within which numerous research articles have been published, the practical use of HRV have reached general consensus only in two clinical applications [45]. That is, it can be used as a predictor of risk after myocardial infarction [24, 19] and as an early warning sign of diabetic neuropathy [5, 33]. In addition, HRV has been found to correlate with, e.g., age, mental and physical stress, and attention, see, e.g., the review in [3].

The term HRV refers, in general, to changes in heart beat interval which is a reciprocal of the heart rate. This is also the case here. The starting point for HRV analysis is the ECG recording from which the HRV time series can be extracted. In the formulation of the HRV

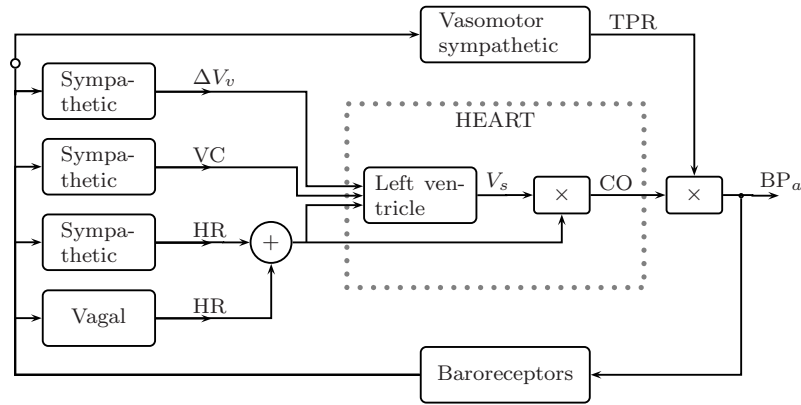


Figure 2.1: The four baroreflex pathways (redrawn from [41]). Variation in venous volume (ΔV_v), left ventricular contractility (VC), sympathetic and parasympathetic (vagal) control of heart rate (HR), stroke volume (V_s), cardiac output (CO), total peripheral resistance (TPR), and arterial blood pressure (BP_a).

time series, a fundamental issue is the determination of heart beat period.

2.1 Heart beat period and QRS detection

The aim in HRV analysis is to examine the sinus rhythm modulated by the autonomic nervous system. Therefore, one should technically detect the occurrence times of the SA-node action potentials. This is, however, practically impossible and, thus, the fiducial points for the heart beat is usually determined from the ECG recording. The nearest observable activity in the ECG compared to SA-node firing is the P-wave resulting from atrial depolarization (see Fig. 2.2) and, thus, the heart beat period is generally defined as the time difference between two successive P-waves. The signal-to-noise ratio of the P-wave is, however, clearly lower than that of the strong QRS complex which results primarily from ventricular depolarization. Therefore, the heart beat period is commonly evaluated as the time difference between the easily detectable QRS complexes.

A typical QRS detector consists of a preprocessing part followed by a decision rule. Several different QRS detectors have been proposed within last decades [46, 34, 35, 17, 12]. For an easy to read review of these methods, see [1]. The preprocessing of the ECG usually includes at least bandpass filtering to reduce power line noise, baseline wander, muscle noise, and other interference components. The passband can be set to approximately 5–30 Hz which covers most of the frequency content of QRS complex [34]. In addition, preprocessing can include differentiation and/or squaring of the samples. After preprocessing, the decision rules are applied to determine whether or not a QRS complex has occurred. The decision rule usually includes an amplitude threshold which is adjusted adaptively as the detection progresses. In addition, the average heart beat period is often used in the decision. The fiducial point is generally selected to be the R-wave and the corresponding time instants are given as the output of the detector.

The accuracy of the R-wave occurrence time estimates is often required to be 1–2 ms and, thus, the sampling frequency of the ECG should be at least 500–1000 Hz [45]. If the

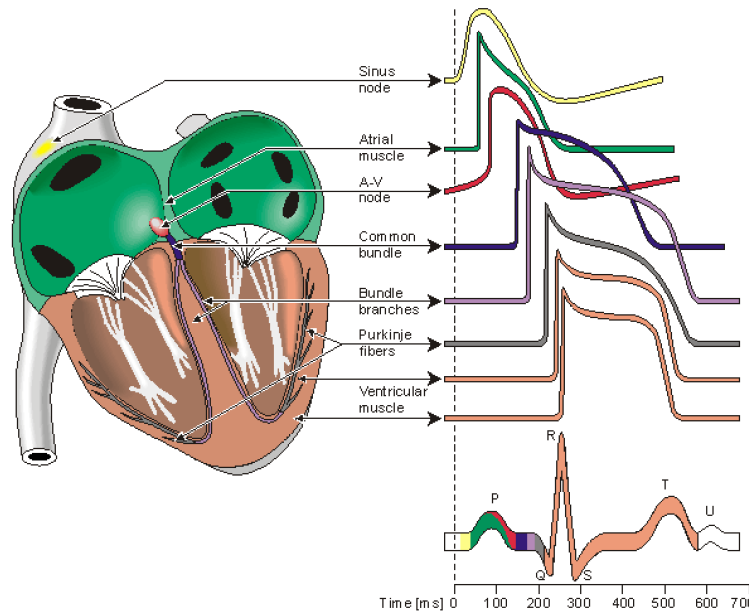


Figure 2.2: Electrophysiology of the heart (redrawn from [26]). The different waveforms for each of the specialized cells found in the heart are shown. The latency shown approximates that normally found in the healthy heart.

sampling frequency of the ECG is less than 500 Hz, the errors in R-wave occurrence times can cause critical distortion to HRV analysis results, especially to spectrum estimates [30]. The distortion of the spectrum is even bigger if the overall variability in heart rate is small [38]. The estimation accuracy can however be improved by interpolating the QRS complex e.g. by using a cubic spline interpolation [9] or some model based approach [4]. It should be, however, noted that when the SA-node impulses are of interest there is an unavoidable estimation error of approximately 3 ms due to fluctuations in the AV-nodal conduction time [41].

2.2 Derivation of HRV time series

After the QRS complex occurrence times have been estimated, the HRV time series can be derived. The inter-beat intervals or RR intervals are obtained as differences between successive R-wave occurrence times. That is, the n 'th RR interval is obtained as the difference between the R-wave occurrence times $RR_n = t_n - t_{n-1}$. In some context, normal-to-normal (NN) may also be used when referring to these intervals indicating strictly intervals between successive QRS complexes resulting from SA-node depolarization [45]. In practice, the NN and RR intervals appear to be the same and, thus, the term RR is preferred here.

The time series constructed from all available RR intervals is, clearly, not equidistantly sampled, but has to be presented as a function of time, i.e. as values (t_n, RR_n) . This fact has to be taken into account before frequency-domain analysis. In general, three different approaches have been used to get around this issue [45]. The simplest approach that have been adopted in, e.g., [2] is to assume equidistant sampling and calculate the spectrum directly from the RR interval tachogram (RR intervals as a function of beat number), see

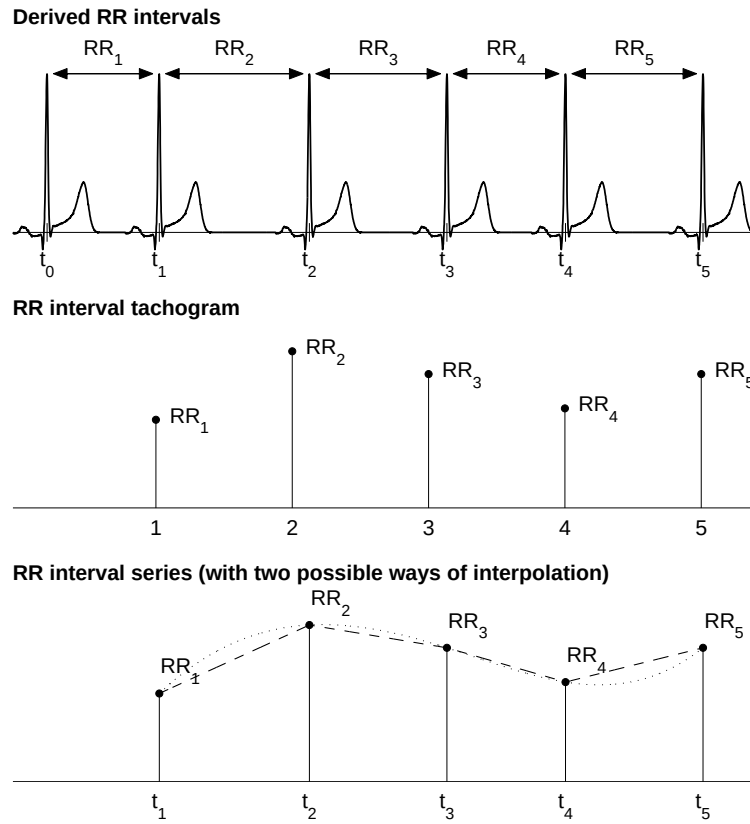


Figure 2.3: Derivation of two HRV signals from ECG: the interval tachogram (middle panel) and interpolated RR interval series (bottom panel).

the left panel of Fig. 2.3. This assumption can, however, cause distortion into the spectrum [28]. This distortion becomes substantial when the variability is large in comparison with the mean level. Furthermore, the spectrum can not be considered to be a function of frequency but rather of cycles per beat [10]. Another common approach, adopted in this software, is to use interpolation methods for converting the non-equidistantly sampled RR interval time series (also called the interval function) to equidistantly sampled [45], see the right panel of Fig. 2.3. One choice for the interpolation method is the cubic spline interpolation [28]. After interpolation, regular spectrum estimation methods can be applied. The third general approach called the spectrum of counts considers a series of impulses (delta functions positioned at beat occurrence times) [11]. This approach relies on the generally accepted *integral pulse frequency modulator* (IPFM) which aims to model the neural modulation of the SA-node [41]. According to this model, the modulating signal is integrated until a reference level is achieved after which an impulse is emitted and the integrator is set to zero. The spectrum of the series of events can be calculated, e.g., by first lowpass filtering the event series and then calculating the spectrum of the resulting signal [10].

2.3 Preprocessing of HRV time series

Any artifact in the RR interval time series may interfere the analysis of these signals. The artifacts within HRV signals can be divided into technical and physiological artifacts. The technical artifacts can include missing or additional QRS complex detections and errors in R-wave occurrence times. These artifacts may be due to measurement artifacts or the computational algorithm. The physiological artifacts, on the other hand, include ectopic beats and arrhythmic events. In order to avoid the interference of such artifacts, the ECG recording and the corresponding event series should always be manually checked for artifacts and only artifact-free sections should be included in the analysis [45]. Alternatively, if the amount of artifact-free data is insufficient, proper interpolation methods can be used to reduce these artifacts, see, e.g., [21, 22, 29].

Another common feature that can alter the analysis significantly are the slow linear or more complex trends within the analyzed time series. Such slow nonstationarities are characteristic for HRV signals and should be considered before the analysis. The origins of nonstationarities in HRV are discussed, e.g., in [3]. Two kinds of methods have been used to get around the nonstationarity problem. In [49], it was suggested that HRV data should be systematically tested for nonstationarities and that only stationary segments should be analyzed. Representativeness of these segments in comparison with the whole HRV signal was, however, questioned in [15]. Other methods try to remove the slow nonstationary trends from the HRV signal before analysis. The detrending is usually based on first order [23, 31] or higher order polynomial [39, 31] models. In addition, this software includes an advanced detrending procedure originally presented in [44]. This approach is based on smoothness priors regularization.

2.3.1 Smoothness priors based detrending approach

Let $z \in \mathbb{R}^N$ denote the RR interval time series which can be considered to consist of two components

$$z = z_{\text{stat}} + z_{\text{trend}} \quad (2.1)$$

where z_{stat} is the nearly stationary RR interval series of interest, z_{trend} is the low frequency aperiodic trend component, and N is the number of RR intervals. Suppose that the trend component can be modeled with a linear observation model as

$$z_{\text{trend}} = H\theta + e \quad (2.2)$$

where $H \in \mathbb{R}^{N \times p}$ is the observation matrix, $\theta \in \mathbb{R}^p$ are the regression parameters, and e is the observation error. The task is then to estimate the parameters by some fitting procedure so that $\hat{z}_{\text{trend}} = H\hat{\theta}$ can be used as the estimate of the trend. The properties of the estimate depend strongly on the properties of the basis vectors (columns of the matrix H) in the fitting. A widely used method for the solution of the estimate $\hat{\theta}$ is the least squares method. However, a more general approach for the estimation of $\hat{\theta}$ is used here. That is, the so-called regularized least squares solution

$$\hat{\theta}_\lambda = \arg \min_{\theta} \{ \|z - H\theta\|^2 + \lambda^2 \|D_d(H\theta)\|^2 \} \quad (2.3)$$

where λ is the regularization parameter and D_d indicates the discrete approximation of the d 'th derivative operator. This is clearly a modification of the ordinary least squares solution to the direction in which the side norm $\|D_d(H\theta)\|$ gets smaller. In this way, prior information

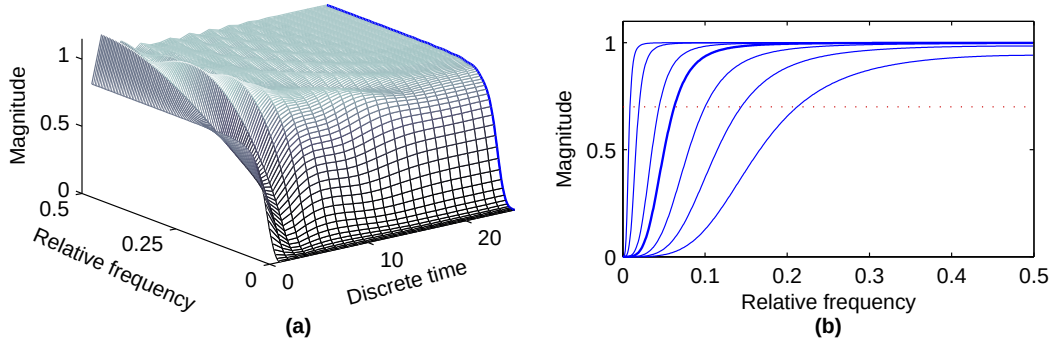


Figure 2.4: a) Time-varying frequency response of $\mathcal{L}$ ($N - 1 = 50$ and $\lambda = 10$). Only the first half of the frequency response is presented, since the other half is identical. b) Frequency responses, obtained from the middle row of $\mathcal{L}$ (cf. bold lines), for $\lambda = 1, 2, 4, 10, 20, 100$, and 500 . The corresponding cut-off frequencies are $0.213, 0.145, 0.101, 0.063, 0.045, 0.021$ and 0.010 times the sampling frequency.

about the predicted trend $H\theta$ can be implemented to the estimation. The solution of (2.3) can be written in the form

$$\hat{\theta}_\lambda = (H^T H + \lambda^2 H^T D_d^T D_d H)^{-1} H^T z \quad (2.4)$$

and the estimate for the trend which is to be removed as

$$\hat{z}_{\text{trend}} = H \hat{\theta}_\lambda. \quad (2.5)$$

The selection of the observation matrix H can be implemented according to some known properties of the data z . For example, a generic set of Gaussian shaped functions or sigmoids can be used. Here, however, the trivial choice of identity matrix $H = I \in \mathbb{R}^{N \times N}$ is used. In this case, the regularization part of (2.3) can be understood to draw the solution towards the null space of the regularization matrix D_d . The null space of the second order difference matrix contains all first order curves and, thus, D_2 is a good choice for estimating the aperiodic trend of RR series. With these specific choices, the detrended nearly stationary RR series can be written as

$$\hat{z}_{\text{stat}} = z - H \hat{\theta}_\lambda = (I - (I + \lambda^2 D_2^T D_2)^{-1}) z. \quad (2.6)$$

In order to demonstrate the properties of the proposed detrending method, its frequency response is considered. Equation (2.5) can be written as $\hat{z}_{\text{stat}} = \mathcal{L}z$, where $\mathcal{L} = I - (I + \lambda^2 D_2^T D_2)^{-1}$ corresponds to a time-varying finite impulse response highpass filter. The frequency response of $\mathcal{L}$ for each discrete time point, obtained as a Fourier transform of its rows, is presented in Fig. 2.4 (a). It can be seen that the filter is mostly constant but the beginning and end of the signal are handled differently. The filtering effect is attenuated for the first and last elements of z and, thus, the distortion of end points of data is avoided. The effect of the smoothing parameter λ on the frequency response of the filter is presented in Fig. 2.4 (b). The cutoff frequency of the filter decreases when λ is increased. Besides the λ parameter the frequency response naturally depends on the sampling rate of signal z .

Chapter 3

Analysis methods

In this chapter, the analysis methods used in the software are introduced. The presented methods are mainly based on the guidelines given in [45]. The presentation of the methods is divided into three categories, i.e. time-domain, frequency-domain and nonlinear methods. The methods summarized in Table 3.1.

3.1 Time-domain methods

The time-domain methods are the simplest to perform since they are applied straight to the series of successive RR interval values. The most evident such measure is the mean value of RR intervals ($\overline{RR}$) or, correspondingly, the mean HR ($\overline{HR}$). In addition, several variables that measure the variability within the RR series exist. The standard deviation of RR intervals (SDNN) is defined as

$$SDNN = \sqrt{\frac{1}{N-1} \sum_{j=1}^N (RR_j - \overline{RR})^2} \quad (3.1)$$

where RR_j denotes the value of j 'th RR interval and N is the total number of successive intervals. The SDNN reflects the overall (both short-term and long-term) variation within the RR interval series, whereas the standard deviation of successive RR interval differences (SDSD) given by

$$SDSD = \sqrt{E\{\Delta RR_j^2\} - E\{\Delta RR_j\}^2} \quad (3.2)$$

can be used as a measure of the short-term variability. For stationary RR series $E\{\Delta RR_j\} = E\{RR_{j+1}\} - E\{RR_j\} = 0$ and SDSD equals the root mean square of successive differences (RMSSD) given by

$$RMSSD = \sqrt{\frac{1}{N-1} \sum_{j=1}^{N-1} (RR_{j+1} - RR_j)^2}. \quad (3.3)$$

Another measure calculated from successive RR interval differences is the NN50 which is the number of successive intervals differing more than 50 ms or the corresponding relative amount

$$pNN50 = \frac{NN50}{N-1} \times 100\%. \quad (3.4)$$

In addition to the above statistical measures, there are some geometric measures that are calculated from the RR interval histogram. The HRV triangular index is obtained as the integral of the histogram (i.e. total number of RR intervals) divided by the height of the histogram which depends on the selected bin width. In order to obtain comparable results, a bin width of 1/128 seconds is recommended [45]. Another geometric measure is the TINN which is the baseline width of the RR histogram evaluated through triangular interpolation, see [45] for details.

3.2 Frequency-domain methods

In the frequency-domain methods, a *power spectrum density* (PSD) estimate is calculated for the RR interval series. The regular PSD estimators implicitly assume equidistant sampling and, thus, the RR interval series is converted to equidistantly sampled series by interpolation methods prior to PSD estimation. In the software a cubic spline interpolation method is used. In HRV analysis, the PSD estimation is generally carried out using either FFT based methods or parametric AR modeling based methods. For details on these methods see, e.g., [27]. The advantage of FFT based methods is the simplicity of implementation, while the AR spectrum yields improved resolution especially for short samples. Another property of AR spectrum that has made it popular in HRV analysis is that it can be factorized into separate spectral components. The disadvantages of the AR spectrum are the complexity of model order selection and the contingency of negative components in the spectral factorization. Nevertheless, it may be advantageous to calculate the spectrum with both methods to have comparable results.

In this software, the HRV spectrum is calculated with FFT based Welch's periodogram method and with the AR method. Spectrum factorization in AR method is optional. In the Welch's periodogram method the HRV sample is divided into overlapping segments. The spectrum is then obtained by averaging the spectra of these segments. This method decreases the variance of the FFT spectrum.

The generalized frequency bands in case of short-term HRV recordings are the very low frequency (VLF, 0–0.04 Hz), low frequency (LF, 0.04–0.15 Hz), and high frequency (HF, 0.15–0.4 Hz). The frequency-domain measures extracted from the PSD estimate for each frequency band include absolute and relative powers of VLF, LF, and HF bands, LF and HF band powers in normalized units, the LF/HF power ratio, and peak frequencies for each band (see Table 3.1). In the case of FFT spectrum, absolute power values for each frequency band are obtained by simply integrating the spectrum over the band limits. In the case of AR spectrum, on the other hand, if factorization is enabled distinct spectral components emerge for each frequency band with a proper selection of the model order and the absolute power values are obtained directly as the powers of these components. If factorization is disabled the AR spectrum powers are calculated as for the FFT spectrum. The band powers in relative and normalized units are obtained from the absolute values as described in Table 3.1.

3.3 Nonlinear methods

Considering the complex control systems of the heart it is reasonable to assume that nonlinear mechanisms are involved in the genesis of HRV. The nonlinear properties of HRV have been analyzed using measures such as Poincaré plot [6, 7], approximate and sample entropy [40, 13], detrended fluctuation analysis [36, 37], correlation dimension [16, 18], and

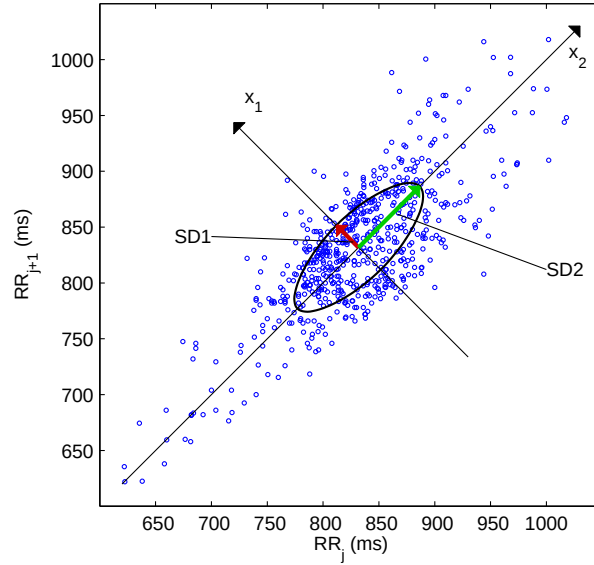


Figure 3.1: Poincaré plot analysis with the ellipse fitting procedure. SD1 and SD2 are the standard deviations in the directions x_1 and x_2 , where x_2 is the line-of-identity for which $RR_j = RR_{j+1}$.

recurrence plots [48, 47, 50]. During the last years, the number of studies utilizing such methods have increased substantially. The downside of these methods is still, however, the difficulty of physiological interpretation of the results.

3.3.1 Poincaré plot

One commonly used nonlinear method that is simple to interpret is the so-called Poincaré plot. It is a graphical representation of the correlation between successive RR intervals, i.e. plot of RR_{j+1} as a function of RR_j as described in Fig. 3.1. The shape of the plot is the essential feature. A common approach to parameterize the shape is to fit an ellipse to the plot as shown in Fig. 3.1. The ellipse is oriented according to the line-of-identity ($RR_j = RR_{j+1}$) [6]. The standard deviation of the points perpendicular to the line-of-identity denoted by SD1 describes short-term variability which is mainly caused by RSA. It can be shown that SD1 is related to the time-domain measure SDD according to [6]

$$SD1^2 = \frac{1}{2} SDD^2. \quad (3.5)$$

The standard deviation along the line-of-identity denoted by SD2, on the other hand, describes long-term variability and has been shown to be related to time-domain measures SDNN and SDD by [6]

$$SD2^2 = 2 SDNN^2 - \frac{1}{2} SDD^2. \quad (3.6)$$

The standard Poincaré plot can be considered to be of the first order. The second order plot would be a three dimensional plot of values $(RR_j, RR_{j+1}, RR_{j+2})$. In addition, the lag can be bigger than 1, e.g., the plot (RR_j, RR_{j+2}) .

3.3.2 Approximate entropy

Approximate entropy (ApEn) measures the complexity or irregularity of the signal [13, 40]. Large values of ApEn indicate high irregularity and smaller values of ApEn more regular signal. The ApEn is computed as follows.

First, a set of length m vectors u_j is formed

$$u_j = (\text{RR}_j, \text{RR}_{j+1}, \dots, \text{RR}_{j+m-1}), \quad j = 1, 2, \dots, N - m + 1 \quad (3.7)$$

where m is called the embedding dimension and N is the number of measured RR intervals. The distance between these vectors is defined as the maximum absolute difference between the corresponding elements, i.e.,

$$d(u_j, u_k) = \max \{ |\text{RR}_{j+n} - \text{RR}_{k+n}| \mid n = 0, \dots, m-1 \}. \quad (3.8)$$

Next, for each u_j the relative number of vectors u_k for which $d(u_j, u_k) \leq r$ is calculated. This index is denoted with $C_j^m(r)$ and can be written in the form

$$C_j^m(r) = \frac{\text{nbr of } \{u_k \mid d(u_j, u_k) \leq r\}}{N - m + 1} \quad \forall k. \quad (3.9)$$

Due to the normalization, the value of $C_j^m(r)$ is always smaller or equal to 1. Note that the value is, however, at least $1/(N - m + 1)$ since u_j is also included in the count. Then, take the natural logarithm of each $C_j^m(r)$ and average over j to yield

$$\Phi^m(r) = \frac{1}{N - m + 1} \sum_{j=1}^{N-m+1} \ln C_j^m(r). \quad (3.10)$$

Finally, the approximate entropy is obtained as

$$\text{ApEn}(m, r, N) = \Phi^m(r) - \Phi^{m+1}(r). \quad (3.11)$$

Thus, the value of the estimate ApEn depends on three parameters, the length m of the vectors u_j , the tolerance value r , and the data length N . In this software the value of m is selected to be $m = 2$. The length N of the data also affects ApEn. When N is increased the ApEn approaches its asymptotic value. The tolerance r has a strong effect on ApEn and it should be selected as a fraction of the standard deviation of the data (SDNN). This selection enables the comparison of different data types. A common selection for r is $r = 0.2\text{SDNN}$, which is also used in this software.

3.3.3 Sample entropy

Sample entropy (SampEn) is similar to ApEn, but there are two important differences in its calculation [40, 20]. For ApEn, in the calculation of the number of vectors u_k for which $d(u_j, u_k) \leq r$ also the vector u_j itself is included. This ensures that $C_j^m(r)$ is always larger than 0 and the logarithm can be applied, but at the same time it makes ApEn to be biased. In sample entropy the self-comparison of u_j is eliminated by calculating $C_j^m(r)$ as

$$C_j^m(r) = \frac{\text{nbr of } \{u_k \mid d(u_j, u_k) \leq r\}}{N - m} \quad \forall k \neq j. \quad (3.12)$$

Now the value of $C_j^m(r)$ will be between 0 and 1. Next, the values of $C_j^m(r)$ are averaged to yield

$$C^m(r) = \frac{1}{N - m + 1} \sum_{j=1}^{N-m+1} C_j^m(r) \quad (3.13)$$

and the sample entropy is obtained as

$$\text{SampEn}(m, r, N) = \ln(C^m(r)/C^{m+1}(r)). \quad (3.14)$$

The values selected for the embedding dimension m and for the tolerance parameter r in the software are the same as those for the approximate entropy calculation. Both ApEn and SampEn are estimates for the negative natural logarithm of the conditional probability that a data of length N , having repeated itself within a tolerance r for m points, will also repeat itself for $m + 1$ points. SampEn was designed to reduce the bias of ApEn and has a closer agreement with the theory for data with known probabilistic content [20].

3.3.4 Detrended fluctuation analysis

Detrended fluctuation analysis (DFA) measures the correlation within the signal. The correlation is extracted for different time scales as follows [36]. First, the RR interval time series is integrated

$$y(k) = \sum_{j=1}^k (\text{RR}_j - \overline{\text{RR}}), \quad k = 1, \dots, N \quad (3.15)$$

where $\overline{\text{RR}}$ is the average RR interval. Next, the integrated series is divided into segments of equal length n . Within each segment, a least squares line is fitted into the data. Let $y_n(k)$ denote these regression lines. Next the integrated series $y(k)$ is detrended by subtracting the local trend within each segment and the root-mean-square fluctuation of this integrated and detrended time series is calculated by

$$F(n) = \sqrt{\frac{1}{N} \sum_{k=1}^N (y(k) - y_n(k))^2}. \quad (3.16)$$

This computation is repeated over different segment lengths to yield the index $F(n)$ as a function of segment length n . Typically $F(n)$ increases with segment length. A linear relationship on a double log graph indicates presence of fractal scaling and the fluctuations can be characterized by scaling exponent α (the slope of the regression line relating $\log F(n)$ to $\log n$. Different values of α indicate the following

$\alpha = 1.5$:	Brown noise (integral of white noise)
$1 < \alpha < 1.5$:	Different kinds of noise
$\alpha = 1$:	$1/f$ noise
$0.5 < \alpha < 1$:	Large values are likely to be followed by large value and vice versa
$\alpha = 0.5$:	white noise
$0 < \alpha < 0.5$:	Large value is likely to be followed by small value and vice versa

Typically, in DFA the correlations are divided into short-term and long-term fluctuations. In the software, the short-term fluctuations are characterized by the slope α_1 obtained from the $(\log n, \log F(n))$ graph within range $4 \leq n \leq 16$. Correspondingly, the slope α_2 obtained from the range $16 \leq n \leq 64$ characterizes long-term fluctuations, see Fig. 3.2.

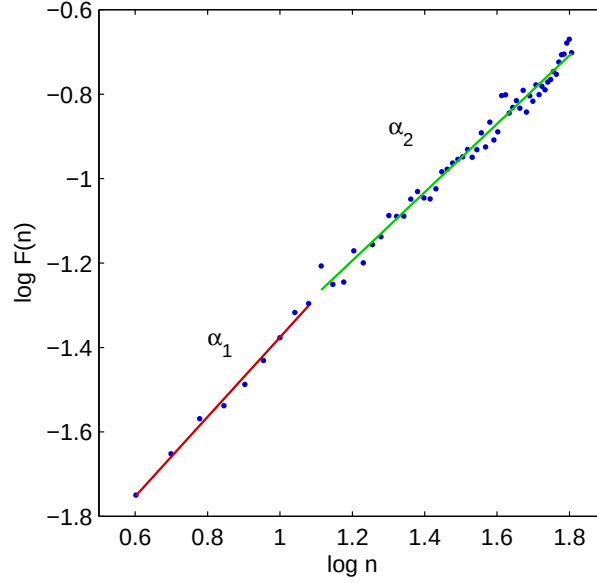


Figure 3.2: Detrended fluctuation analysis. A double log plot of the index $F(n)$ as a function of segment length n . α_1 and α_2 are the short term and long term fluctuation slopes, respectively.

3.3.5 Correlation dimension

Another method for measuring the complexity or strangeness of the time series is the correlation dimension which was proposed in [14]. The correlation dimension is expected to give information on the minimum number of dynamic variables needed to model the underlying system and it can be obtained as follows.

Similarly as in the calculation of approximate and sample entropies, form length m vectors u_j

$$u_j = (RR_j, RR_{j+1}, \dots, RR_{j+m-1}), \quad j = 1, 2, \dots, N - m + 1 \quad (3.17)$$

and calculate the number of vectors u_k for which $d(u_j, u_k) \leq r$, that is

$$C_j^m(r) = \frac{\text{nbr of } \{u_k \mid d(u_j, u_k) \leq r\}}{N - m + 1} \quad \forall k \quad (3.18)$$

where the distance function $d(u_j, u_k)$ is now defined as

$$d(u_j, u_k) = \sqrt{\sum_{l=1}^m (u_j(l) - u_k(l))^2}. \quad (3.19)$$

Next, an average of the term $C_j^m(r)$ is taken

$$C^m(r) = \frac{1}{N - m + 1} \sum_{j=1}^{N-m+1} C_j^m(r) \quad (3.20)$$

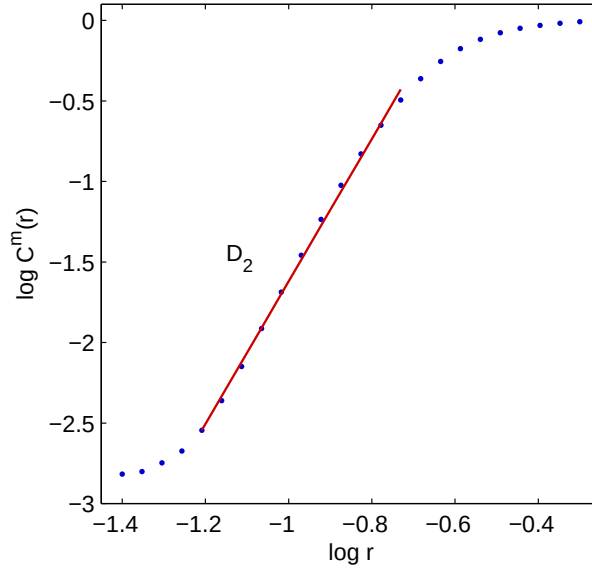


Figure 3.3: Approximation of the correlation dimension D_2 from the $(\log r, \log C^m(r))$ plot.

which is the so-called correlation integral. The correlation dimension D_2 is defined as the limit value

$$D_2(m) = \lim_{r \rightarrow 0} \lim_{N \rightarrow \infty} \frac{\log C^m(r)}{\log r}. \quad (3.21)$$

In practice this limit value is approximated by the slope of the regression curve $(\log r, \log C^m(r))$ [18]. The slope is calculated from the linear part of the log-log plot, see Fig. 3.3. The slope of the regression curves tend to saturate on the finite value of D_2 when m is increased. In the software, a value of $m = 10$ was selected for the embedding.

3.3.6 Recurrence plot analysis

Yet another approach, included in the software, for analyzing the complexity of the time series is the so-called *recurrence plot* (RP) analysis. In this approach, vectors

$$u_j = (RR_j, RR_{j+\tau}, \dots, RR_{j+(m-1)\tau}), \quad j = 1, 2, \dots, N - (m-1)\tau \quad (3.22)$$

where m is the embedding dimension and τ the embedding lag. The vectors u_j then represent the RR interval time series as a trajectory in m dimensional space. A recurrence plot is a symmetrical $[N - (m-1)\tau] \times [N - (m-1)\tau]$ matrix of zeros and ones. The element in the j 'th row and k 'th column of the RP matrix, i.e. $RP(j, k)$, is 1 if the point u_j on the trajectory is close to point u_k . That is

$$RP(j, k) = \begin{cases} 1, & d(u_j - u_k) \leq r \\ 0, & \text{otherwise} \end{cases} \quad (3.23)$$

where $d(u_j, u_k)$ is the Euclidean distance given in (3.19) and r is a fixed threshold. The structure of the RP matrix usually shows short line segments of ones parallel to the main diagonal. The lengths of these diagonal lines describe the duration of which the two points are close to each other. An example RP for HRV time series is presented in Fig. 3.4.

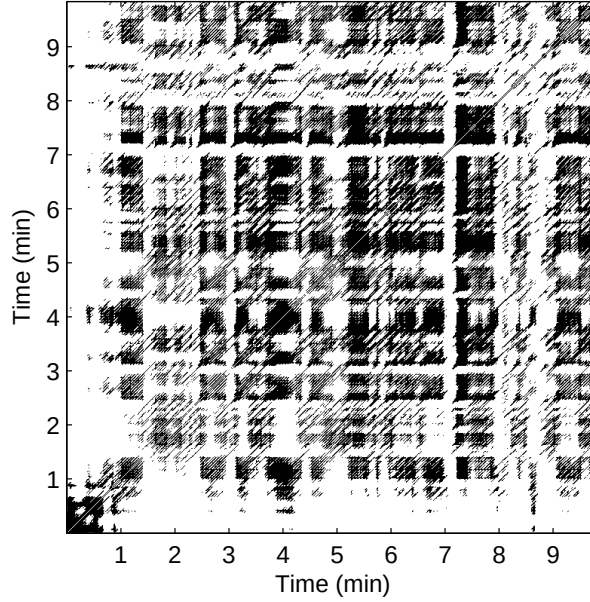


Figure 3.4: Recurrence plot matrix for HRV time series (black = 1 and white = 0).

Methods for quantifying recurrence plots were proposed in [48]. The methods included in this software are introduced below.

In the software the following selections were made. The embedding dimension and lag were selected to be $m = 10$ and $\tau = 1$, respectively. The threshold distance r was selected to be $\sqrt{m}$ SD, where SD is the standard deviation of the RR time series. The selection are similar to those made in [8].

The first quantitative measure of RP is the *recurrence rate* (REC) which is simply the ratio of ones and zeros in the RP matrix. The number of elements in the RP matrix for $\tau = 1$ is equal to $N - m + 1$ and the recurrence rate is simply given as

$$\text{REC} = \frac{1}{(N - m + 1)^2} \sum_{j,k=1}^{N-m+1} \text{RP}(j, k). \quad (3.24)$$

The recurrence rate can also be calculated separately for each diagonal parallel to the line-of-identity (main diagonal). The trend of REC as a function of the time distance between these diagonals and the line-of-identity describes the fading of the recurrences for points further away.

The rest of the RP measures consider the lengths of the diagonal lines. A threshold $l_{\min} = 2$ is used for excluding the diagonal lines formed by tangential motion of the trajectory. The maximum line length is denoted $l_{\max}$ and its inverse, the divergence,

$$\text{DIV} = \frac{1}{l_{\max}} \quad (3.25)$$

has been shown to correlate with the largest positive Lyapunov exponent [47]. The average diagonal line length, on the other hand, is obtained as

$$l_{\text{mean}} = \frac{\sum_{l=l_{\min}}^{l_{\max}} l N_l}{\sum_{l=l_{\min}}^{l_{\max}} N_l} \quad (3.26)$$

where N_l is the number of length l lines. The determinism of the time series is measured by the variable

$$\text{DET} = \frac{\sum_{l=l_{\min}}^{l_{\max}} l N_l}{\sum_{j,k=1}^{N-m+1} \text{RP}(j,k)}. \quad (3.27)$$

Finally, the Shannon information entropy of the line length distribution is defined as

$$\text{ShanEn} = - \sum_{l=l_{\min}}^{l_{\max}} n_l \ln n_l \quad (3.28)$$

where n_l is the number of length l lines divided by the total number of lines, that is

$$n_l = \frac{N_l}{\sum_{l'=l_{\min}}^{l_{\max}} N_{l'}}. \quad (3.29)$$

3.4 Summary of HRV parameters

The presented time-domain, frequency-domain and nonlinear measures of HRV calculated by the software are summarized in Table 3.1. For each measure, preferred units and a short description is given. In addition, a reference to the equation in which the specific measure is defined is given when possible and related references are given for some of the measures.



Table 3.1: Summary of the HRV measures calculated by the software

	Measure	Units	Description	References
Time-Domain	$\overline{RR}$	[ms]	The mean of RR intervals	
	STD RR (SDNN)	[ms]	Standard deviation of RR intervals [Eq. (3.1)]	
	$\overline{HR}$	[1/min]	The mean heart rate	
	STD HR	[1/min]	Standard deviation of instantaneous heart rate values	
	RMSSD	[ms]	Square root of the mean squared differences between successive RR intervals [Eq. (3.3)]	
	NN50		Number of successive RR interval pairs that differ more than 50 ms	
	pNN50	[%]	NN50 divided by the total number of RR intervals [Eq. (3.4)]	
	HRV index triangular		The integral of the RR interval histogram divided by the height of the histogram	[45]
	TINN	[ms]	Baseline width of the RR interval histogram	[45]
Frequency-Domain	Peak frequency	[Hz]	VLF, LF, and HF band peak frequencies	
	Absolute power	[ms ²]	Absolute powers of VLF, LF, and HF bands	
	Relative power	[%]	Relative powers of VLF, LF, and HF bands VLF [%] = VLF [ms ²]/total power [ms ²] × 100% LF [%] = LF [ms ²]/total power [ms ²] × 100% HF [%] = HF [ms ²]/total power [ms ²] × 100%	
	Normalized power	[n.u.]	Powers of LF and HF bands in normalized units LF [n.u.] = LF [ms ²]/(total power [ms ²] - VLF [ms ²]) HF [n.u.] = HF [ms ²]/(total power [ms ²] - VLF [ms ²])	
	LF/HF		Ratio between LF and HF band powers	
	SD1, SD2	[ms]	The standard deviation of the Poincaré plot perpendicular to (SD1) and along (SD2) the line-of-identity	[6, 7]
	ApEn		Approximate entropy [Eq. (3.11)]	[40, 13]
Nonlinear	SampEn		Sample entropy [Eq. (3.14)]	[40]
	D_2		Correlation dimension [Eq. (3.21)]	[16, 18]
	DFA		Detrended fluctuation analysis:	[36, 37]
	α_1		Short term fluctuation slope	
	α_2		Long term fluctuation slope	
	RPA		Recurrence plot analysis:	[48, 8, 50]
	Lmean	[beats]	Mean line length [Eq. (3.26)]	
	Lmax	[beats]	Maximum line length	
	REC	[%]	Recurrence rate [Eq. (3.24)]	
	DET	[%]	Determinism [Eq. (3.27)]	
	ShanEn		Shannon entropy [Eq. (3.28)]	



Chapter 4

Software description

4.1 Input data formats

Kubios HRV supports the following RR interval file formats. First of all, data of two commonly used heart rate monitors is supported. These are SUUNTO SDF/STE and POLAR HRM files. When analyzing data of these devices it should however be noted that the RR intervals must be measured/stored in beat-to-beat. In addition, a support for plain RR interval ASCII text files is provided. The input ASCII file can include either RR interval values or ECG data in one or two column format. That is, The RR interval values can be given as

Type 1	Type 2	
0.759	0.759	0.759
0.690	1.449	0.690
0.702	2.151	0.702
0.712	2.863	0.712
0.773	3.636	0.773
⋮	⋮	⋮

The RR interval values above are given in seconds, but millisecond values can also be given.

4.2 The user interface

The developed HRV analysis software is operated with a graphical user interface. This user interface window is shown in Fig. 4.1. The user interface is divided into four segments: 1) the RR interval series options segment on the top left corner, 2) the data browser segment on the top right corner, 3) the analysis options segment on the bottom left corner, and 4) the results view segment on the bottom right corner. Each of these segments are described in Sections 4.2.1, 4.2.2, 4.2.3, and 4.2.4, respectively.

4.2.1 RR interval series options

The RR interval series options shown in Fig. 4.2 include three functions: *Artifact correction*, *Samples for analysis*, and *Remove trend components*. The artifact correction options can be

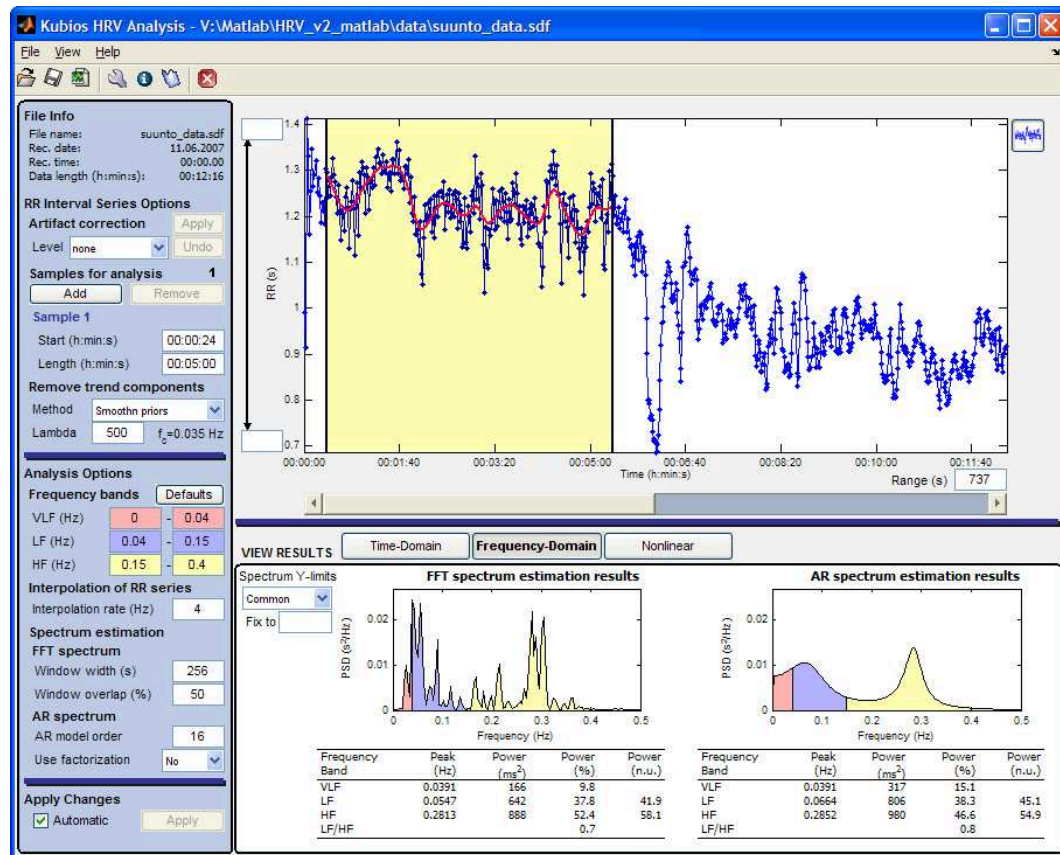


Figure 4.1: The graphical user interface of the developed HRV analysis software.

used to correct artifacts from a corrupted RR interval series. The user can select between very low, low, medium, strong, and very strong correction levels. In addition, a custom level in seconds can be set. The corrections to be made on the RR series are displayed on the RR interval axis. To make the corrections press the Apply button. A piecewise cubic spline interpolation method is used in the corrections. You can reverse the correction by pressing the Undo button or by selecting none as the correction level. It should be noted that artifact correction generates missing or corrupted values into the RR series by interpolation and can cause distortion into the analysis results.

An example of artifact correction can be seen in Fig. 4.3. In this case, the analyzed RR interval sample includes two clear artifacts. In order to remove these artifacts a medium level correction was selected. The effect of correction can be verified from the user interface, i.e. the corrected series is displayed on top of the raw RR interval series as can be seen from Fig. 4.3 (a). The correction level can be accepted and the correction performed by pressing the Apply button. The corrected series is shown in Fig. 4.3 (b). As can be seen from the spectrum estimates in Figs. 4.3 (a) and (b), the correction of just few artifacts has a very significant effect on the analysis results. Thus, even single artifacts should always be taken care of prior to HRV analysis.

In the *Samples for analysis* options the part(s) of the RR interval series to be analyzed can be modified by adding or removing samples and by changing the start time or length of

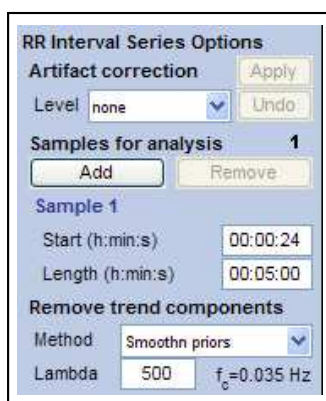


Figure 4.2: The RR interval series options segment of the user interface.

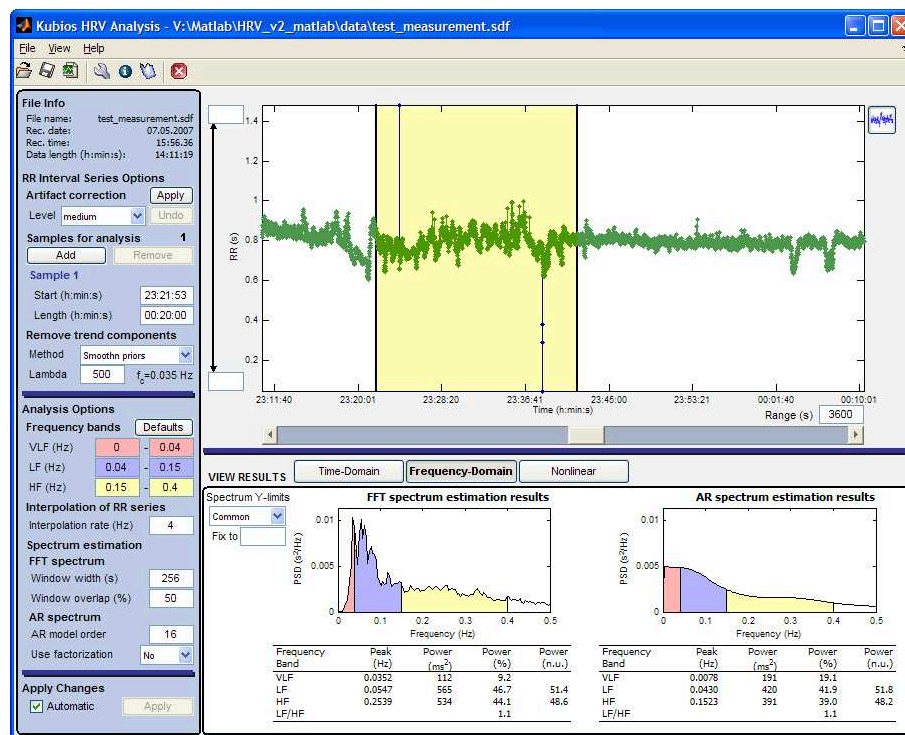
the sample. If more than one sample is selected, the analysis can be done either for the single samples separately or by merging the samples into one long sample before analysis. This selection is visible under the RR series axis when multiple samples are selected. The starting point and length of the samples can also be changed by moving/resizing the patch over the RR series as described in Section 4.2.2. This section also describes how to add/remove samples to/from RR series axes.

Sometimes the RR interval time series includes a disturbing low frequency baseline trend component. Detrending options can be used to remove this kind of trend components. Detrending options include removal of the first, second, or third order linear trend or the trend can be removed using a method called smoothness priors which was presented in [44]. In the smoothness priors method, the smoothness of the removed trend can be adjusted by editing the Lambda value. The smoothness priors method is basically a time-varying high pass filter and its cut-off frequency can be adjusted with the Lambda parameter (the bigger the value of Lambda the smoother is the removed trend). The estimated cut-off frequency for the given Lambda value is presented next to the Lambda value edit box. In addition, the trend to be removed from the RRI series is shown over the selected part of the RR series as a red line.

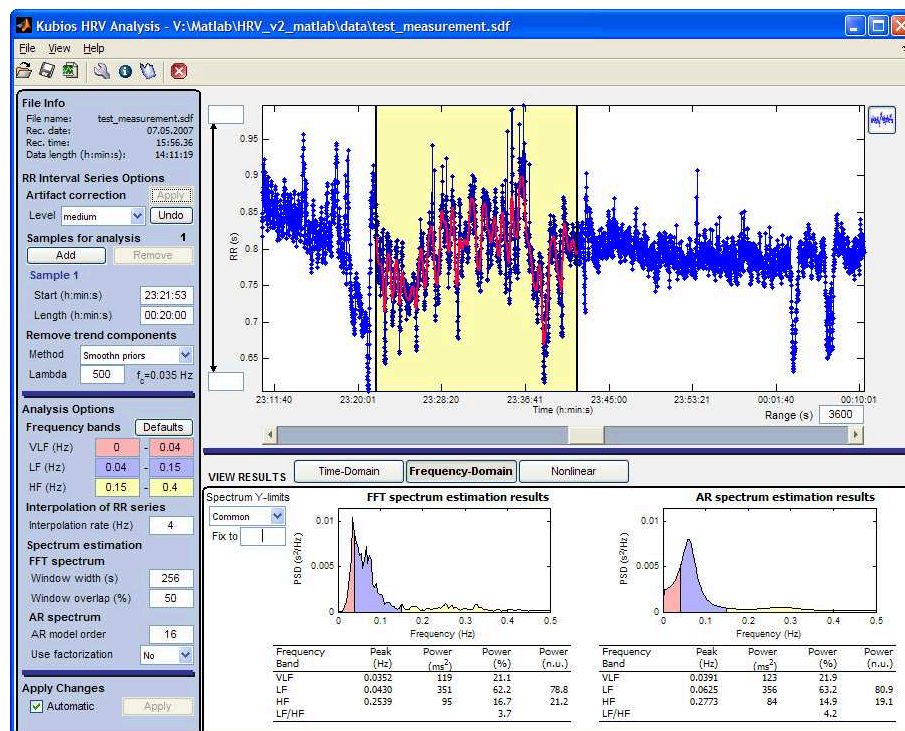
4.2.2 Data browser

The data browser segment shown in Fig. 4.4 displays the measured RR interval series. The RR interval data can be scrolled with the slider and the range of the axis can be changed by editing the Range value. The RR series display mode can be changed with the button on the right hand side of the RR axis. In addition, the Y-limit of the axis can be manually changed by editing the edit boxes on the left hand side of the axis. In addition to the visualization of the RR interval data, the RR interval axis displays also the artifact corrections described in Section 4.2.1.

The selected sample(s) (yellow patches in the RR axis) can be modified with mouse as follows. Each sample can be moved by grabbing it from the middle with the left mouse button and resized by grabbing it from the left or right edge. You can also add a new sample to a specific location in the RR series by right clicking the RR axis. The new sample will start from the clicked time instant and the length of the new sample is by default same as the previous sample. After right clicking the RR axis a small popup window opens in which the sample start time and length can be accepted/modified. When more than one



(a)



(b)

Figure 4.3: Artifact correction: (a) the artifact corrected series is visualized on top of the raw RR interval series. (b) Corrected RR interval series.



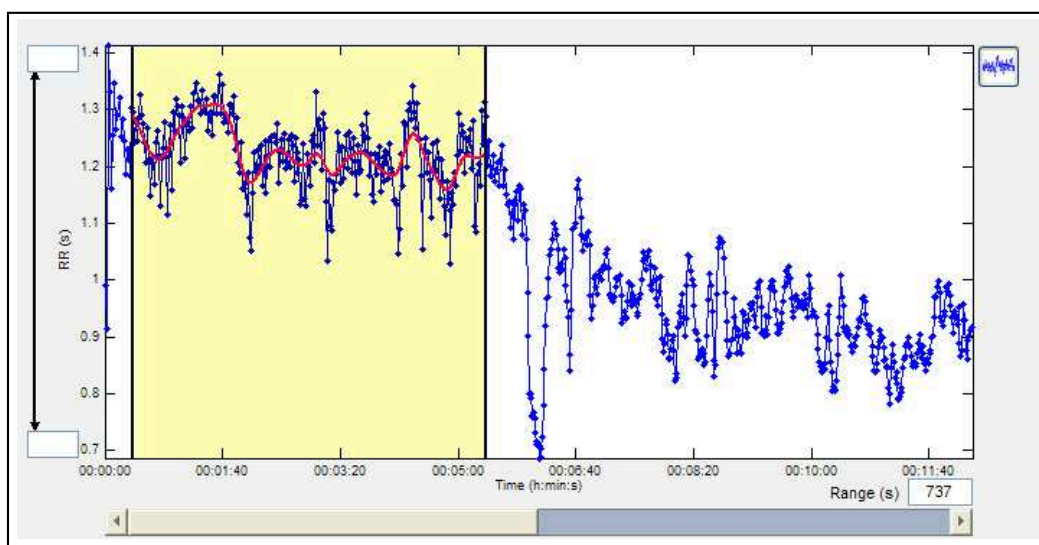


Figure 4.4: The data browser segment of the user interface.

Analysis Options		
Frequency bands Defaults		
VLF (Hz)	0	- 0.04
LF (Hz)	0.04	- 0.15
HF (Hz)	0.15	- 0.4
Interpolation of RR series		
Interpolation rate (Hz)	4	
Spectrum estimation		
FFT spectrum		
Window width (s)	256	
Window overlap (%)	50	
AR spectrum		
AR model order	16	
Use factorization	No	

Figure 4.5: The analysis options segment of the user interface.

samples are selected, a sample can be removed by right clicking it with the mouse.

4.2.3 Analysis options

The analysis options segment shown in Fig. 4.5 includes three subcategories: *Frequency bands*, *Interpolation of RR series*, and *Spectrum estimation*. All of these options are concerned with frequency-domain analysis.

The very low frequency (VLF), low frequency (LF), and high frequency (HF) bands of HRV frequency-domain analysis can be adjusted by editing the VLF, LF, and HF values. The default values for the bands are VLF: 0–0.04 Hz, LF: 0.04–0.15 Hz, and HF: 0.15–0.4 Hz according to [45]. The default values for the bands can be restored by pressing the Defaults button.

The RR interval time series is an irregularly time sampled series as discussed in Section 2.2 and, thus, spectrum estimation methods can not be applied directly. In this software, this problem is solved by using interpolation methods for converting the RR series into equidistantly sampled form. As the interpolation method a piecewise cubic spline interpolation is used. The sampling rate of the interpolation can be adjusted by editing the Interpolation rate value. By default a 4 Hz interpolation is used.

The spectrum for the selected RR interval sample is calculated both with Welch's periodogram method (FFT spectrum) and with an autoregressive modeling based method (AR spectrum). In the Welch's periodogram method, the used window width and window overlap can be adjusted by editing the corresponding value. The default value for window width is 256 seconds and the default overlap is 50 % (corresponding to 128 seconds). In the AR spectrum, there are also two options that can be selected. First, the order of the used AR model can be selected. The default value for the model order is 16, but the model order should always be at least twice the number of spectral peaks in the data. The second option is whether or not to use spectral factorization in the AR spectrum estimation. In the factorization the AR spectrum is divided into separate components and the power estimates of each component are used for the band powers. The factorization, however, has some serious problems which can distort the results significantly. The main problems are the selection of the model order in such a way that only one AR component will result in each frequency band and, secondly, negative power values can result for closely spaced AR components. Thus, the selection of not to use factorization in AR spectrum is surely more robust and in that sense recommended.

4.2.4 Results view

The results for the selected RR interval sample are displayed in the results view segment. The results are divided into time-domain, frequency-domain and nonlinear results. The results of each section are displayed by pressing the corresponding button on the top of the results view segment. The results are by default updated automatically whenever any one of the the sample or analysis options that effect on the results is changed. The updating of the results can be time consuming for longer samples and in that case it might be useful to disable the automatic update by unchecking the Automatic check box in the bottom left corner of the user interface. When unchecked, one or more changes to options can be made without updating breaks and when finished with changes the Apply button can be pressed to update the results.

The time-domain results view shown in Fig. 4.6 displays the time-domain variables in a table and the RR interval and heart rate histograms in the two axes. Most of the results are calculated from the detrended RR series (if detrending is applied), but there are two obvious exceptions (i.e. mean RR interval and mean HR) which are marker with the * symbol.

The frequency-domain results view shown in Fig. 4.7 displays the results for both FFT and AR spectrum estimation methods. Both methods are applied to the detrended RR series. The spectra of the two methods are presented in the two axes (FFT spectrum on the left and AR spectrum on the right). The frequency axes of the spectra are fixed to range from 0 Hz to the upper limit of HF band plus 0.1 Hz. Thus, for the default frequency band settings the frequency axis range is 0–0.5 Hz. The power axes of the spectra, on the other hand, can be adjusted with the options on the upper left corner of the frequency-domain results view. The power axes can be selected to have either common or separate upper Y-limits. If common Y-limit is selected, it can also be entered manually into the edit box below the selection button. The selected power axis options apply also for the report sheet. The results for both spectra are displayed in tables below the corresponding spectrum axes.

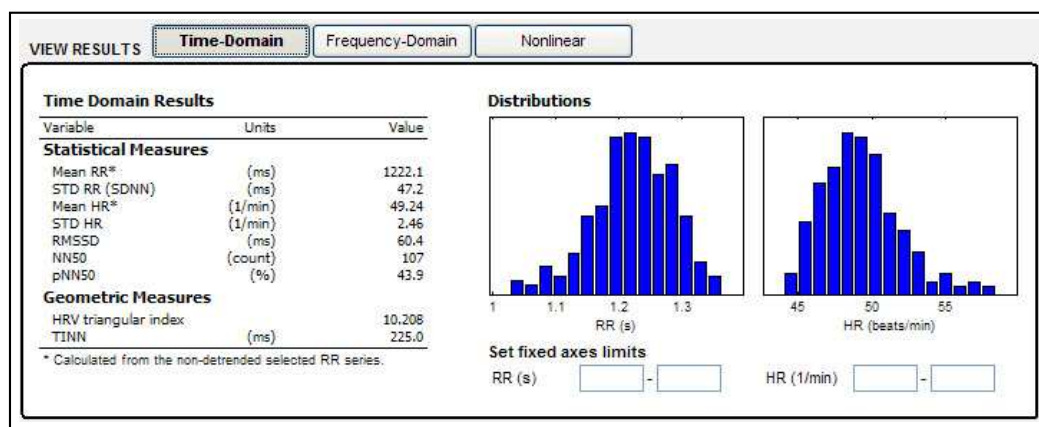


Figure 4.6: The results view segment of the user interface: time-domain results view selected.

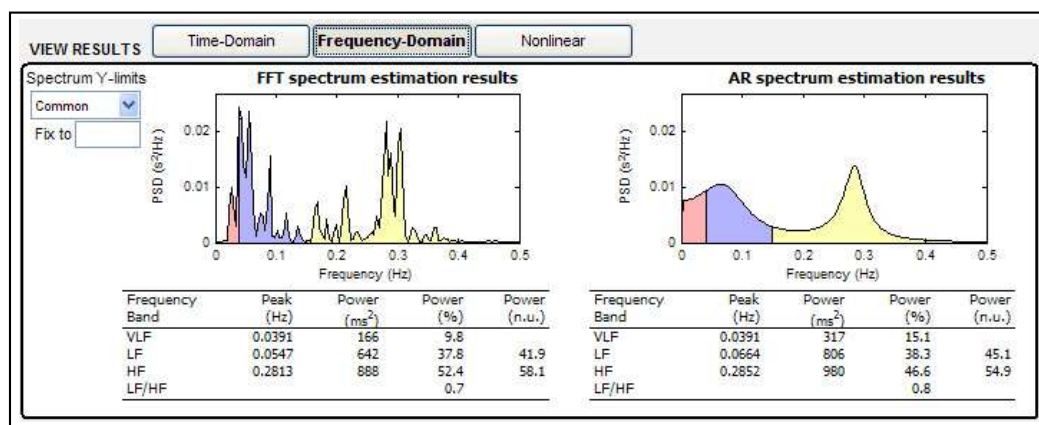


Figure 4.7: The results view segment of the user interface: frequency-domain results view selected.

The nonlinear results view shown in Fig. 4.8 displays all the calculated nonlinear variables in one table. All the variables are calculated from the original non-detrended RR series. The Poincaré plot and the DFA results are also presented graphically in the two axes. In the Poincaré plot (left hand axis), the successive RR intervals are plotted as blue circles and the SD1 and SD2 variables obtained from the ellipse fitting technique are presented (for details see Section 3.3.1). In the DFA plot (right hand axis), the detrended fluctuations $F(n)$ are presented as a function of n in a log-log scale and the slopes for the short term and long term fluctuations α_1 and α_2 , respectively, are indicated (for details see Section 3.3.4).

4.2.5 Menus and toolbar buttons

The user menus and toolbar buttons are located on the upper left hand corner of the user interface. There are all together three user menus and seven toolbar buttons. The toolbar button icons and their actions are given below



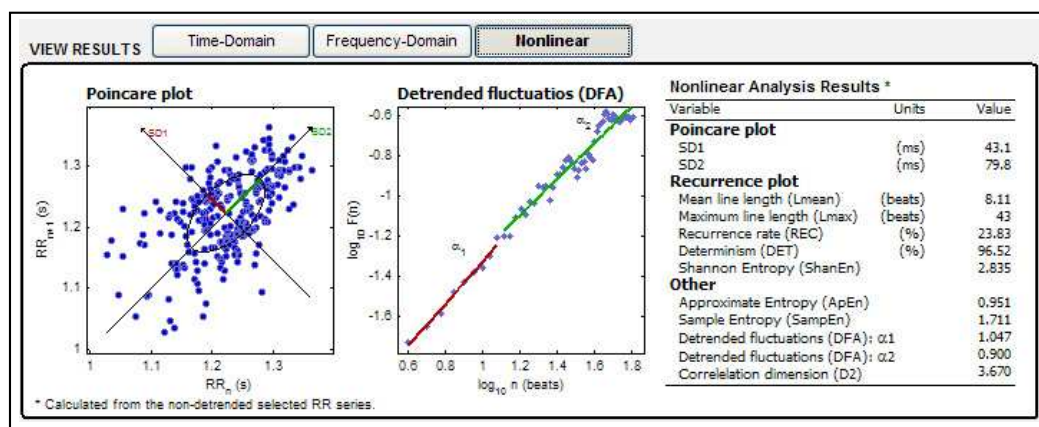


Figure 4.8: The results view segment of the user interface: nonlinear results view selected.



Open new data file button is for opening a new data file for analysis. If the results of the current analysis have not been saved, user is prompted to do so.



Save results button is for saving the analysis results. The results can be saved in ASCII, PDF, and MATLAB® MAT file format (see Section 4.3 for details).



Print results button is for printing the current results without opening report sheet windows.



Report sheet button opens one or several report sheet windows which include all the analysis results (see Section 4.3.2 for details).



Edit preferences button opens a preferences window in which you can, e.g., change the default values for analysis options (see Section 4.4 for details).



About HRV analysis software button opens the about dialog of the software which includes the version number and contact information. Also the Kubios HRV End User License Agreement can be viewed in the about dialog.



Open Kubios HRV User's Guide button opens the Kubios HRV User's Guide (this document) PDF-file using the default PDF viewer of the system.



Close file button closes the current data file. If the results of the current analysis have not been saved, user is prompted to do so.

All the above actions are also available on the user menus. The File menu includes Open, Save Results, Save Results As, Print Results, Edit Preferences, Close, and Quit commands. The Open, Save Results, Edit Preferences, and Close commands work exactly as the corresponding toolbar buttons. The difference between the Save and Save As commands is that when the results have already been saved, the Save command automatically overwrites these results, whereas the Save As command asks the user for a new file name. The Quit command of the File menu is for exiting from the software. The View menu includes Report sheet command which works similarly as the corresponding toolbar button. Finally, the Help menu includes the About HRV Analysis Software command which opens the same about dialog as the corresponding toolbar button.

4.3 Saving the results

The analysis results can be saved by selecting Save Results or Save Results As from the File menu or by pressing the save button on the toolbar. This will open a file save dialog in which the saving type can be selected. There are three different types in which the results can be saved. That is, the results can be written in an ASCII text file for further inspection, the report sheets generated from the results can be saved in a PDF-file, or the results can be saved in a MATLAB® MAT-file.

4.3.1 ASCII-file

When the ASCII text file is selected for the saving type, the numeric results of the analysis will be written in an ASCII text file. The resulting text file includes the following information in the enumerated order.

1. Software, user, and data file informations
2. Used analysis parameters
3. Samples selected for analysis
4. Time-domain results
5. Frequency-domain results
6. Nonlinear results
7. RR interval data and spectrum estimates

The columns of the file are separated with semicolons so that the results could easily be imported to, e.g., spreadsheet programs such as the Microsoft Excel® for further inspection.

4.3.2 Report sheet

The software generates a printable report sheet which present all the analysis results. The report sheet, shown in Fig. 4.9, includes all the time-domain, frequency-domain, and nonlinear analysis results. The RR interval data and the sample selected for analysis are presented on the two axes on top of both sheet and the analysis results below them. If multiple analysis samples have been selected, a report sheet is generated for each sample.

When Save Results have been selected, the report sheet(s) can be saved in a single PDF-file by selecting Report figure as the saving type in the save dialog. In this case, the report sheet(s) will not be displayed, but just saved in the selected PDF-file. If you wish to view the report sheet(s) and/or to export it into some other file format choose Report sheet from the View menu or just press the corresponding toolbar button. This will open the report sheet windows for view.

The report sheet window includes 7 toolbar buttons and File and Page menus on the upper left hand corners of the windows. The toolbar button icons and their actions are given below

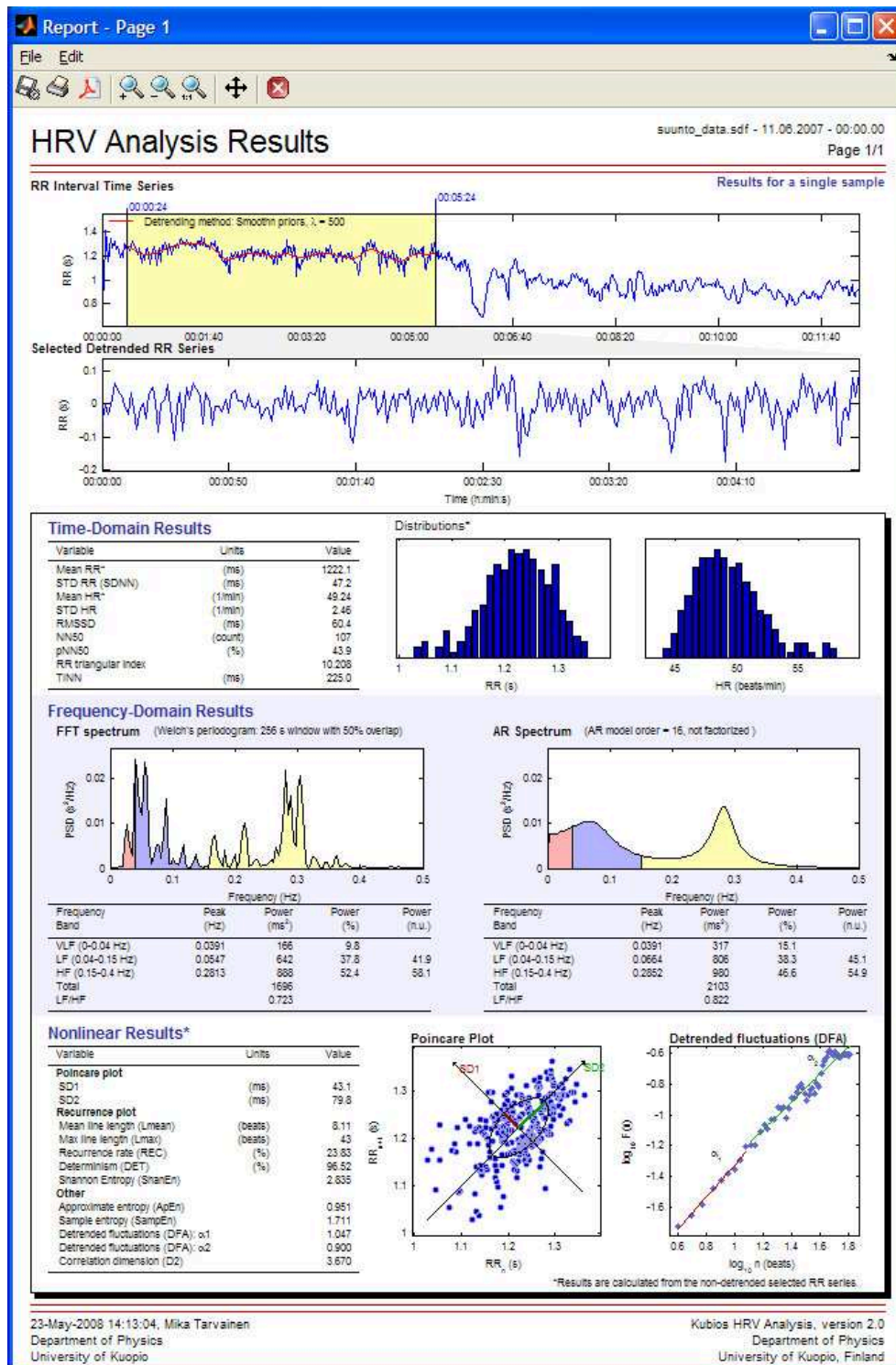


Figure 4.9: The first report sheet including all the time-domain, frequency-domain, and nonlinear analysis results calculated by the software.





Print button opens a print dialog from which the report sheet can be sent to the selected printer.



Export all pages to PDF-file button is for exporting all report sheets into a single PDF-file.



Zoom in button is for zooming in (magnifying) the report sheet.



Zoom out button is for zooming out the report sheet.



Reset to original size button can be used to restore the original zoom level. This also resets the size of the corresponding report sheet window to its original size.



Move visible area button is for moving the visible area of the zoomed report sheet in the report window (just grab the sheet with mouse and drag it to the desired direction).



Close button is for closing the report sheet.

The File menu includes Export All to PDF, Print Current Page, Print All Pages, Close, and Close All commands. The Export All to PDF, Print All Pages, and Close commands are also given as toolbar buttons described above. The last command Close All can be used for closing all report sheets simultaneously. The Edit menu (Windows version only) contains Copy to Clipboard option, which copies the contents of the corresponding report sheet window to the Windows clipboard. This can be used to quickly copying the report sheet as an image into another program. The Page menu includes commands for changing for the previous or the next report sheet page and for changing the sheet by its page number. However, the Page menu is not shown if only one report sheet window is open.

4.3.3 MATLAB® MAT-file

In addition to saving the numeric results into an ASCII text file or saving the report sheet(s) in a PDF-file, the analysis results can also be saved in a MATLAB® MAT-file (compatible with MATLAB® R12 or higher). The MAT-file includes a single structured array variable named Res. The Res variable includes the numeric results as well as the RR interval data and all the analysis options. This saving option is aimed for MATLAB users and makes the further analysis or processing of the HRV data in MATLAB much easier. The Res structure includes four fields which are shortly described as follows

- f_name:** File name of the analyzed data file
- f_path:** Full path for the analyzed data file
- CNT:** Basic information of the data file (the field name refers to Neuroscan CNT-file for historical reasons)
- HRV:** Used analysis options, RR interval data, and all analysis results.

The HRV field is clearly the most essential one of these fields. The HRV field includes six fields the contents of which are shortly described as follows



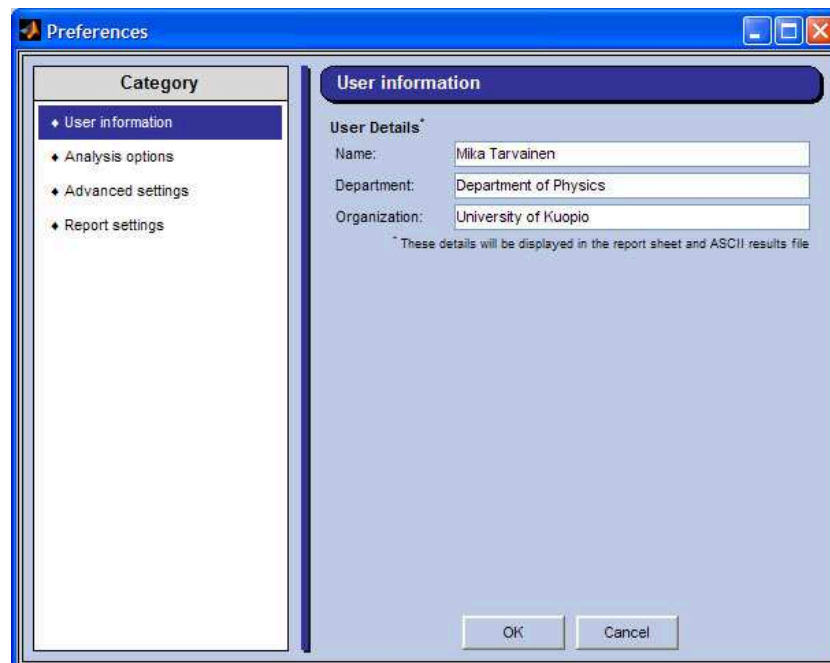


Figure 4.10: Set up preferences window of the software: User information category.

Param: The analysis options used in the calculation of the results
 Data: The RR interval data
 Statistics: Time-domain analysis results
 Frequency: Frequency-domain analysis results
 NonLinear: Nonlinear analysis results

The variable names of the different fields are more or less self-descriptive and are not documented here.

4.4 Setting up the preferences

All the analysis options that can be adjusted in the user interface have some default values. These preference values will be used every time the program is started. Any changes made on these values in the user interface only apply for the current session. The preference values are designed to be more or less suitable for short-term HRV recordings and may sometimes need to be redefined. This can be done by selecting Edit Preferences from the File menu or by pressing the corresponding toolbar button. This will open the preferences window in which the preference values can be redefined. The preferences are divided into four categories: User information, Analysis options, Advanced settings, and Report settings.

In the **User information category** shown in Fig. 4.10 you can set up your personal contact information (Name, Department, and Organization). This information will only be included in the bottom left corner of the report sheet and in the beginning of the ASCII text file including the analysis results. That is, the user information is meant just for indicating the person who has carried out the analysis.

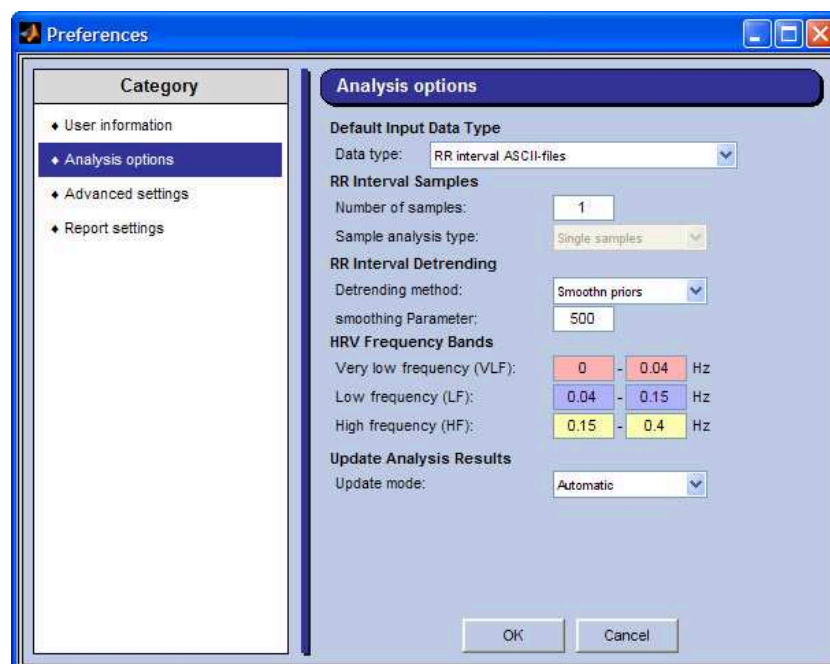


Figure 4.11: Set up preferences window of the software: Analysis options category.

The **Analysis options category** shown in Fig. 4.11 includes some basic analysis options. The default input data type can be set to one of the file formats mentioned in Section 4.1 and the selected data type will be used as default every time a new data file is opened. In addition, the analysis options category includes RR interval samples, RR interval detrending, HRV frequency bands, and Update analysis results options which have already been described in Sections 4.2.1, 4.2.3, and 4.2.4.

The **Advanced settings category** shown in Fig. 4.12 includes Spectrum estimation options. The spectrum estimation options include one additional option compared to those described in Section 4.2.3, i.e. points in frequency-domain option. The point in frequency-domain is given as points/Hz and corresponds by default to the window width of the FFT spectrum. If spectrum interpolation is desired the points in frequency-domain can be increased.

The **Report settings category** shown in Fig. 4.13 includes the following options. The paper size of the report sheet can be changed between A4 (210×297 mm) and Letter (8.5×11 inch) size. The default paper size is A4. In addition, the field delimiter and decimal point used when saving the results in an ASCII file can be selected. The Custom Print Command option allows the use of an external program to print the report sheets in PostScript format.

All modifications for the preferences are saved by pressing the OK button. Note that the OK button saves the preferences, but they will be applied only in the next session. A session is considered to be ended when the program is restarted or Close file is selected. If, on the other hand, a new file is opened (without first closing the previous file) preferences will not be applied, but the local settings (changes made in the user interface) are applied for the new file as well.

In addition to the actual analysis options, there are various other editable options which have mainly influence on the usability of the software. Such options are e.g. the Range

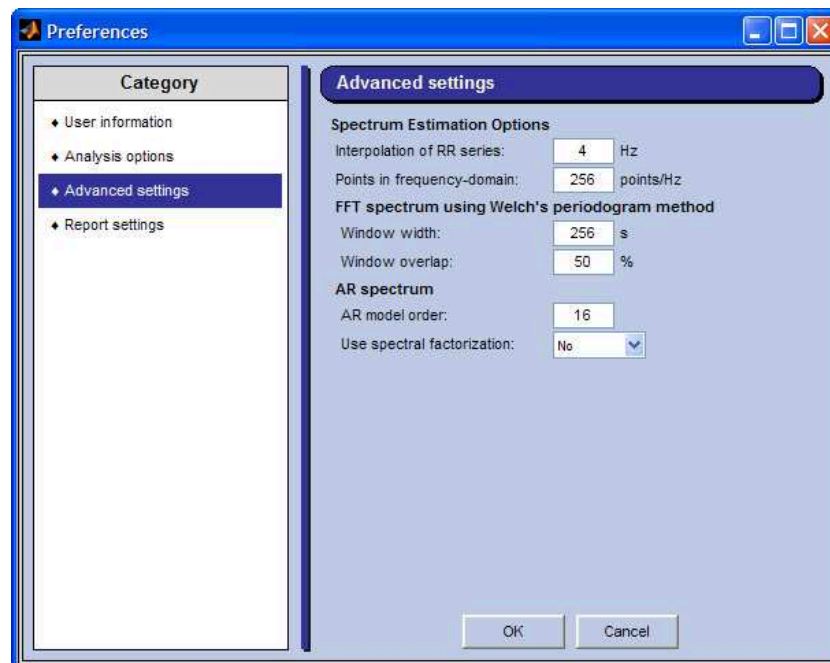


Figure 4.12: Set up preferences window of the software: Advanced settings category.

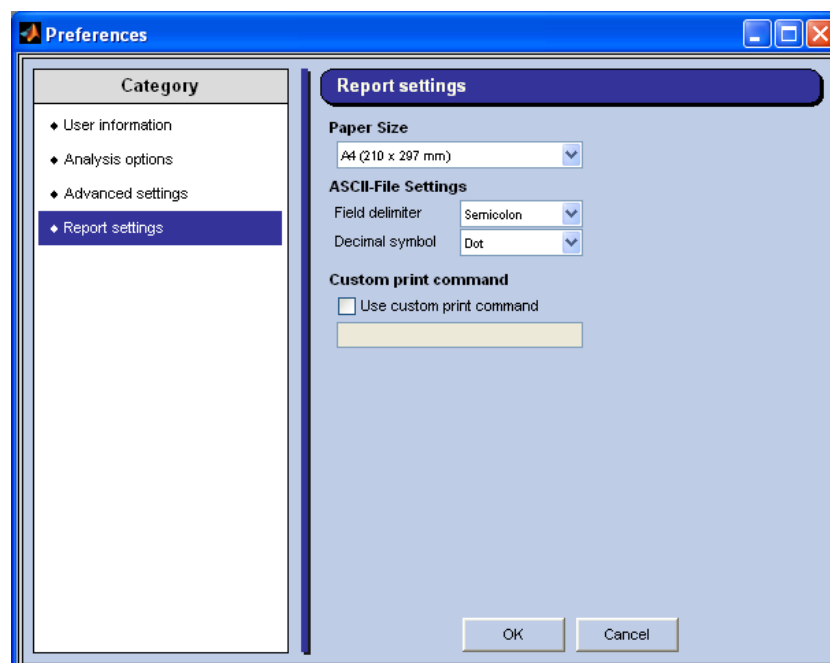


Figure 4.13: Set up preferences window of the software: Report settings category.

and Y-limit values of the data axis and various visualization options. The values of these options are preserved in memory and any changes made to them will be applied in the future sessions. Also the preference directories path from where the data file is searched for and in which the results are saved are preserved in memory. The last nine opened data files will also appear in the File menu of the user interface and can be reopened from there.

All the preferences and preserved options used by Kubios HRV are saved in user specific folders¹.

Windows XP:

```
C:\Documents and Settings\\Application Data\KubiosHRV
```

Windows Vista:

```
C:\Users\\AppData\Roaming\KubiosHRV
```

Linux:

```
/home/<username>/.kubioshrv
```

where <username> is the name of your user profile. The folder will include three files: `hrv_pref.dat`, `user_pref.dat`, and `HRVprefs.mat`. The `hrv_pref.dat` file includes all the preferences for the analysis options, `user_pref.dat` includes the user information preferences, and `HRVprefs.mat` all the preferences related to the usability of the software. These files are created when the software is started for the first time and they will be updated whenever the preference values are edited. The original settings of the preferences can be restored by deleting these files.

¹Note that the Application Data folder in Windows XP and AppData folder in Windows Vista are hidden by default and are not visible in the Windows File Explorer if the “Show hidden files and folders” is not selected from the “Folder Options” section of the File Explorer.



Chapter 5

Sample runs

In this chapter, we present a sample run of the software. The sample run is made for the sample data file distributed with this software. The sample data is measured from a healthy young male during an orthostatic test. The change in the posture is known to be reflected in the low frequency and high frequency HRV in an opposite way. That is, when subject stands up after lying for few minutes a strong decrease in the HF power and a more gradual increase in LF power are observed. In addition, a strong increase in heart rate is observed immediately after standing up, which aims to compensate the sudden decrease in blood pressure. In the sample run, this data file is analyzed by considering the lying and standing periods separately.

5.1 Sample run

In this sample run, we show how to make the general analysis, i.e. time-domain, frequency-domain, and nonlinear analysis, for the lying and standing periods of the orthostatic measurement separately. This task can be easily accomplished in a single session. First, start the software and open the data file into the user interface. At this point, you can edit any of the analysis options to fit your demands. If you are about to analyze several data files with the same options, you better make these changes straight to the preferences.

The next thing to do is to select the RR interval samples to be analyzed. First, add a new sample to the RR interval axes because we want to analyze both the lying and standing periods. To do this, you can simply right click the RR axes, press Yes to the Add sample popup window, and OK to verify the sample properties. Now you will have two samples shown as yellow patches in the RR interval axes. Then change the sample ranges to cover the periods of interest as shown in Fig. 5.1. The easiest way to change the samples' ranges is to edit them with the mouse as described in Section 4.2.2, but the ranges can also be changed by editing the Start and Length values in RR interval series options segment. Then check that the Sample analysis type option under the RR axis is set for Single samples. Then, analysis results are calculated for both samples separately. If, on the other hand, Merge samples is selected, then the two samples are first merged into one sample and the analysis results are calculated for this merged sample.

Since we are now only interested in the changes in LF and HF bands, we wish to remove the lowest frequency trend components from the RR series. These trend components affect on the time and frequency-domain variables and, thus, by removing the trend from the data enables these variables to better describe the LF and HF variability which we are interested

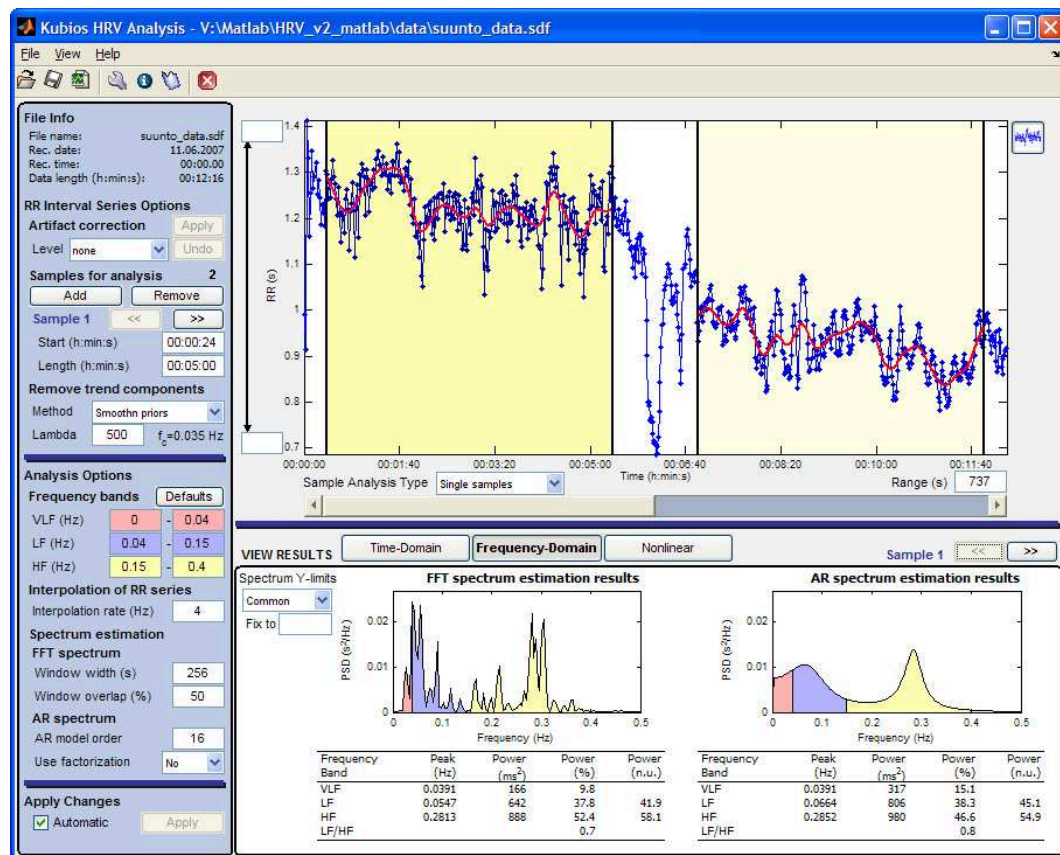


Figure 5.1: Sample run 1.

of. We select to remove the trend with the smoothness priors based method. Once the detrending method is selected red lines appear over the RR interval data indicating the removed trend components. The smoothness of the removed trend in the smoothness priors method can be adjusted by changing the Lambda value. The smoothness priors detrending method can be compared to a high-pass filter in which the cutoff frequency is determined from the lambda value (bigger lambda corresponds to lower cutoff). The estimated cutoff frequency of the detrending method is also shown next to the Lambda value. Since we are now interested in LF and HF frequencies, we wish to make sure that the detrending does not remove those frequencies. This can be easily done by changing the Lambda value in such a way that the cutoff frequency is below 0.04 Hz. The effect of detrending can also be verified by inspecting how it changes the FFT spectrum. Here, we set the Lambda value to 500.

The time-domain, frequency-domain, and nonlinear analysis results for the selected samples can then be viewed in the results view segment. Just make sure that the results have been updated (check that the Automatic is checked in Apply changes and if not press the Apply button). Press the Time-domain, Frequency-domain, or Nonlinear button to view the corresponding results. Note that the results are shown only for one of the samples at a time. To take a look at the results of the other sample press the << or >> button on the top right corner of the results view segment (the text on the left changes to indicate which

sample's results are shown, this sample will also be highlighted in the RR series axis). Note that you can force a common Y-limit for the spectra of both samples by setting a common Y-limit value manually in the frequency-domain results view. For example, we have here fixed the Y-limit value to $0.04 \text{ s}^2/\text{Hz}$.

Once we are done with the analysis, we wish to save the analysis results in all possible formats. This can be done by selecting Save Results from the File menu or just by pressing the save button on the toolbar. Then select **Save all (*.txt,*.mat,*.pdf)** as the save type and enter a file name. You do not need to give any extension to the file name. The numeric results of the analysis will be saved in the ***.txt** text file and in the ***.mat** MATLAB file and the report sheets in the ***.pdf** file. The generated PDF-file will now include two pages, one for the results of the first RR interval sample (the lying period) and one for the second sample (standing period). These report sheet pages are shown in Figs. 5.2 and 5.3. In the text file, the results for the two samples are presented side by side as can be seen from Fig. 5.4.



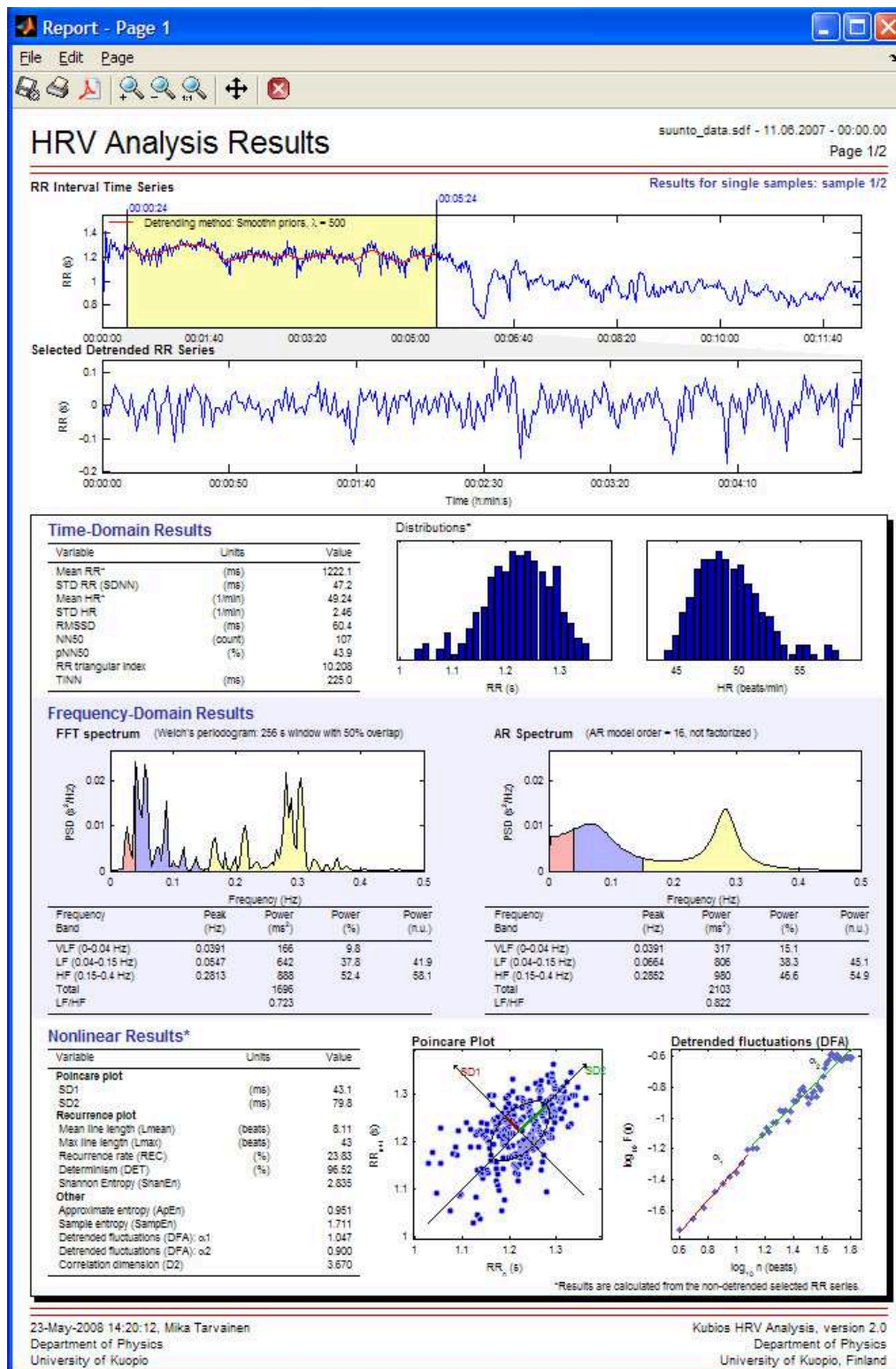


Figure 5.2: Sample run 1, results for the lying period of the orthostatic test.



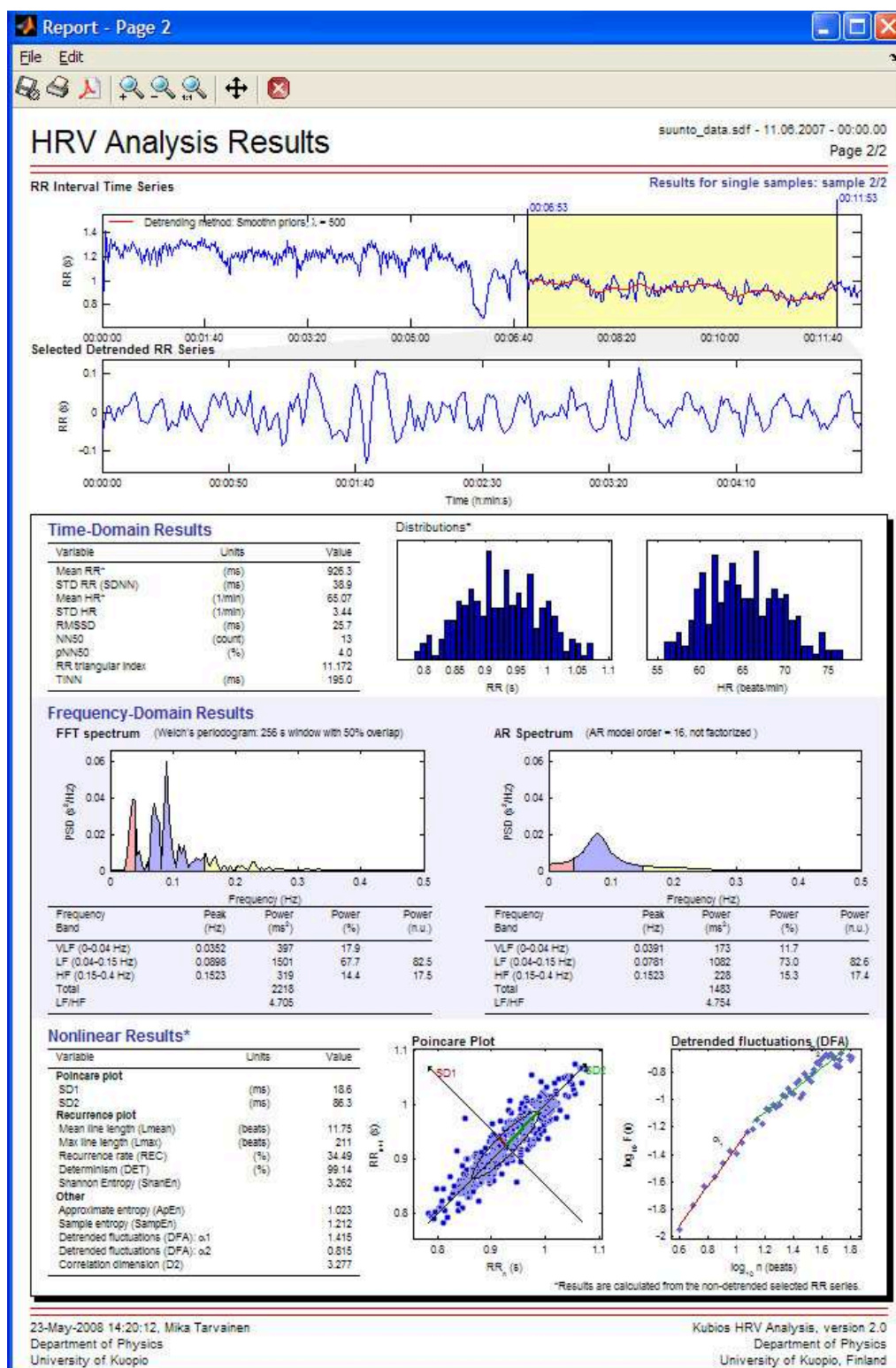


Figure 5.3: Sample run 1, results for the standing period of the orthostatic test.



```

sample_run_1_results.txt - WordPad
File Edit View Insert Format Help

RR Interval Samples Selected for Analysis
; Sample 1; Sample 2;
Sample limits (s): ; 24-324; 415-715;
Sample Analysis Type: Single samples

RESULTS FOR SINGLE SAMPLES
GENERAL RESULTS
; SAMPLE 1; SAMPLE 2;
Time-Domain Results
;
Statistical parameters
;
Mean RR (ms): ; 1221.8694; 926.2515;
STD RR (ms): ; 46.8336; 38.8103;
Mean HR (1/min): ; 49.2438; 65.0716;
STD HR (1/min): ; 2.4456; 3.4238;
RMSSD (ms): ; 60.2684; 25.7229;
NN50 (count): ; 107; 12;
pNN50 (%): ; 43.8525; 3.7152;
SDANN (ms): ; ; ;
SDNN index (ms): ; ; ;
Geometric parameters
;
RR tri index: ; 10.208333; 9.818182;
TINN (ms): ; 225.0000; 190.0000;

Frequency-Domain Results ;FFT spectrum; AR spectrum;FFT spectrum; AR spectrum;
Peak frequencies
;
VLF (Hz): ; 0.039063; 0.039063; 0.039063; 0.039063;
LF (Hz): ; 0.054688; 0.066406; 0.089844; 0.078125;
HF (Hz): ; 0.281250; 0.285156; 0.152344; 0.152344;
Absolute powers
;
VLF (ms^2): ; 164.9878; 298.1608; 390.9904; 179.2697;
LF (ms^2): ; 633.8926; 747.8336; 1491.4383; 1111.4596;
HF (ms^2): ; 883.8326; 1025.3441; 314.5418; 230.0966;
Relative powers
;
VLF (%): ; 9.8049; 14.3946; 17.7968; 11.7877;
LF (%): ; 37.6709; 36.1039; 67.8861; 73.0826;
HF (%): ; 52.5243; 49.5015; 14.3171; 15.1297;
Normalized powers
;
LF (n.u.): ; 41.7660; 42.1748; 82.5833; 82.8485;
HF (n.u.): ; 58.2340; 57.8252; 17.4167; 17.1515;
LF/HF ratio: ; 0.7172; 0.7293; 4.7416; 4.8304;
EDR (Hz): ; 0.283027; ; 0.217069; ;

Nonlinear Results
;
Poincare plot
;
SD1 (ms): ; 43.013247; 18.594375;
SD2 (ms): ; 79.722321; 86.249913;
Recurrence plot analysis (RPA);
;
Mean line length (beats): ; 8.1272; 11.7661;
Max line length (beats): ; 43; 212;
Recurrence rate, REC (%): ; 23.9838; 34.5578;
Determinism, DET (%): ; 96.6163; 99.1659;
Shannon entropy: ; 2.8487; 3.2655;
Detrended fluctuation analysis (DFA);
;
alpha 1: ; 0.9246; 1.3209;
alpha 2: ; 0.8887; 0.8120;
Others
;
Approximate entropy, ApEn: ; 0.9868; 1.0339;
Sample entropy, SampEn: ; 1.7363; 1.2416;
Correlation dimension, D2: ; 3.6877; 3.3227;

For Help, press F1

```

Figure 5.4: Sample run 1, results saved in an ASCII file.



Appendix A

Frequently asked questions

Based on the feedback and user experiences obtained from the users of the previous version of the HRV analysis software [32] we have collected here a bunch of frequently asked questions. An answer to each question is given below the question. Some of the questions are concerned with the optimal value of some analysis parameter. Often these parameter values are, however, more or less case-specific, for example the length of the selected HRV data may change the preferred settings for FFT spectrum calculation. Thus, some of the answers might be more or less vague, but hopefully still helpful.

■ ***When several RR interval samples have been selected, what does the merge samples do?***

When the Merge samples option is selected for the Sample analysis type, the RR interval samples selected for analysis are simply merged into one sample by concatenating the samples.

■ ***How to select the value of λ in the smoothness priors based detrending?***

λ is the regularization parameter in the smoothness priors based detrending approach, see Section 2.3.1 for details. The value of this parameter changes the smoothness of the estimated trend, i.e. a bigger value corresponds to a smoother trend. As discussed in Section 2.3.1 the smoothness priors detrending method can be compared to a time-varying highpass filter and λ adjusts the cut-off frequency of the filter. The estimated cut-off frequency for a given lambda value is now presented next to the lambda value. If you want to make sure that you don't eliminate any frequencies from the LF band, you should select lambda in such a way that the corresponding cut-off frequency is less than the lower limit of the LF band (by default 0.04 Hz).

■ ***How to select the interpolation rate of the RR series?***

The interpolation rate is related to the cubic spline interpolation that is used for converting the RR interval series to equidistantly sampled series. The default value for the interpolation rate is 4 Hz which works well for normal human HRV data. It should be noted that the interpolation rate should be at least twice as high as the highest expected frequency in the RR interval series. When changing the interpolation rate, it should be remembered that it affects on the smoothness priors based detrending method, i.e. when decreasing the interpolation rate also the λ value of the smoothness priors method should be decreased.

■ ***How to select the window width and overlap for the FFT spectrum estimate?***

The FFT spectrum in the software is calculated using the Welch's periodogram method where one or more overlapped segments are extracted from the data. Then FFT spectrum is calculated for each segment and as a result the average of the segment spectra is calculated. The selection of the window width and overlap in this method is simply a trade-off between the frequency resolution and variance of the spectrum estimate. The frequency resolution of FFT spectrum is roughly the reciprocal of the sample length (i.e. the frequency resolution of the FFT spectrum of a 100 second sample is ~ 0.1 Hz). The variance of the FFT spectrum estimate, on the other hand, does not depend on the sample length, but can be decreased by averaging several shorter samples (which leads to decreased frequency resolution).

■ ***How to select the AR model order for the AR spectrum estimate?***

The AR method is a parametric method which can be used also for spectrum estimation. In this method the RR interval series is modeled with an autoregressive model of specific order. The roots of the AR polynomial (which are actually complex conjugate pairs) correspond to the spectral peaks in the AR spectrum. Thus, the order of the AR model has to be at least twice the number of expected spectral peaks in the spectrum. In practice, the order is, however, always higher than this minimum and the few extra roots do not disturb the spectrum estimate. Even though, an exaggerated model order can induce spurious peaks into the AR spectrum estimate and distort the results. The AR model order naturally depends on the interpolation rate of the RR interval series, but in many cases the default order of 16 is reasonable.

■ ***Why do the power values of Kubios HRV 2.0 spectrum estimates differ from those of the version 1.1?***

The differences in power values are due to two changes. First of all, in version 2.0 the mean of the RR interval data is removed before spectrum estimation. This decreases significantly the VLF power value of the FFT based spectrum estimate. Secondly, the scaling of the spectrum estimates is changed as follows. In version 1.1 the spectrum estimates were scaled such that the total power from $0-f_s$ Hz was equal to the variance of the RR data, where f_s is the sampling frequency of the RR data (i.e. the interpolation rate). In version 2.0, on the other hand, the total power from $0-f_s/2$ Hz is equal to the variance.



Appendix B

Troubleshooting

- ***The Kubios HRV seems to take ages to start.***

The MATLAB® Compiler 4 has changed dramatically from the earlier versions. It is now more of a deployment tool than a compiler because it only generates a wrapper executable that starts the MATLAB® Compiler Runtime (MCR) and runs the heavily crypted Matlab M-files of the compiled application on top of the MCR. Although this has many advantages the main disadvantage is that the starting of the MATLAB® Compiler Runtime takes roughly the same time as starting MATLAB®. This can be anything from 10 to 50 seconds depending on the speed of the computer.

B.1 Windows specific

- ***Kubios HRV Analysis fails to start and gives the following error message: “This application has failed to start because MCLMCRRT7x.DLL was not found. Re-installing the application may fix this problem.”.***

This error message is produced if the Kubios HRV executable cannot find the MATLAB® Compiler Runtime (MCR). Verify that you have the MATLAB® Compiler Runtime (v7.x) installed in <KubiosHRV_install_dir>\MCR. If you have the MCR installed and Kubios HRV Analysis still fails to start, make sure that the system path contains the entry for MCR (i.e., the <KubiosHRV_install_dir>\MCR\7x\runtime\win32 directory is found in the system path). Note that in order to modify the system path you need to have administrator privileges.

- ***The quality of printed report sheets is poor with rasterized fonts etc.***

Due to a bug in the MATLAB® Compiler, printing directly to a printer does not work in MATLAB® created standalone applications in Windows platforms. The workaround for this provided by MathWorks creates a bitmap file which it then sends to the printer. The rasterization is a result of this bitmap conversion. There are, however, a few workarounds for this problem. One obvious workaround is to save the report sheet first as a PDF file and print it e.g. using Adobe Reader. Another workaround is to install GhostScript and GSview (<http://pages.cs.wisc.edu/~ghost/>) on your computer and use the

“Use custom print command” option in the Kubios HRV preferences. See <http://pages.cs.wisc.edu/~ghost/gsview/gspaint.htm> for more information.

■ ***I have Matlab R2008a with Compiler toolbox installed on the same computer as Kubios HRV and printing does not work.***

The entry for Matlab in the system path is (usually) before the Matlab Compiler Runtime entry created by Kubios HRV installer. As a consequence, Kubios HRV uses the compiler runtime from the Matlab R2008a Compiler toolbox installation instead of the compiler runtime installed by Kubios HRV installer. The printing, does not work in this situation because Kubios HRV cannot locate `gscript.mexw32`. A workaround is to copy the file `<matlab_root>\toolbox\matlab\graphics\private\gscript.mexw32` to `<matlab_root>\toolbox\matlab\graphics\` folder.

B.2 Linux specific

■ ***I receive the following error when trying to run Kubios HRV from command line: error while loading shared libraries: libmwmclmcrtrt.so: cannot open shared object file: No such file or directory.***

This error is produced when the `kubioshrv` executable cannot locate MATLAB® Compiler Runtime. Do not use the `kubioshrv` executable directly to run Kubios HRV version 2.0. Instead, use the `start_kubioshrv.sh` script which sets up the MATLAB® Compiler Runtime environment and then starts Kubios HRV.

■ ***When I try to print report sheets, I get an error message in the terminal that starts with “java.lang.NullPointerException: null attribute...”***

This error is due to a bug in the communication between Java and CUPS (Common Unix Printing System) 1.3.4. The possible workarounds for this issue are:

- Use the “custom print command” options in the Kubios HRV preferences.
- Set the orientation property to anything else than Automatic for every printer installed on the system. (e.g. in Ubuntu Linux this can be done by opening the printer configuration tool *System→Administration→Printing* and changing the orientation property from the *Job Options* tab for every installed printer.)
- Downgrade you CUPS to older version (not recommended).

References

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